

2I385A / 2I385CW

Intel Bay Trail-I E3815 / E3845 / E3825
(Single Core / Quad Core / Dual Core) CPU,
Intel Bay Trail-D J1900 (Quad Core) CPU,
DDR3L 1066 / 1333 MT/s,
2 x LAN / LVDS / Touch Screen / USB / COM

All-In-One

Intel Bay Trail-I E3815 / E3845 / E3825
(Single Core 1.46 GHz / Quad Core 1.91 GHz / Dual Core 1.33 GHz) CPU,
Intel Bay Trail-D J1900 (Quad Core 2.0 GHz) CPU,
2 x Intel GbE LAN, 2 x PCIe mini card slots,
VGA, Audio, SATA, USB, COM, LVDS, Touch Screen

CAUTION

**RISK OF EXPLOSION IF BATTERY IS REPLACED
BY AN INCORRECT TYPE.**

**DISPOSE OF USED BATTERIES ACCORDING
TO THE INSTRUCTIONS**

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User Manual edition 0.1, SEP. 07. 2017

Warning !

1. Battery
Batteries on board are consumables.
The life time of them are not guaranteed.
2. Fanless solution with HDD
The specification & limitation of HDD should be considered carefully when the fanless solution is implemented.
3. We will not give further notification in case of changes of product information and manual.
4. SATA interface does not support Hot SWAP function.
5. There might be a 20% inaccuracy of WDT at room temperature.
6. Please make sure the voltage specification meets the requirement of equipment before plugging in.
7. There are two types of SSD, commercial grade and industrial grade, which provide different read/write speed performance, operation temperature and life cycle. Please contact sales for further information before making orders.
8. Caution! Please notice that the heat dissipation problem could cause the MB system unstable. Please deal with heat dissipation properly when buying single MB set.
9. Please avoid approaching the heat sink area to prevent users from being scalded with fanless products.
10. If users repair, modify or destroy any component of product unauthorizedly, We will not take responsibility or provide warranty anymore.
11. DO NOT apply any other material which may reduce cooling performance onto the thermal pad.
12. It is important to install a system fan toward the CPU to decrease the possibility of overheating / system hanging up issues, or customer is suggested to have a fine cooling system to dissipate heat from CPU.

* Hardware Notice Guide

1. Before linking power supply with the motherboard, please attach DC-in adapter to the motherboard first. Then plug the adapter power to AC outlet.
Always shut down the computer normally before you move the system unit or remove the power supply from the motherboard. Please unplug the DC-in adapter first and then unplug the adapter from the AC outlet.
Please refer photo 1 as standard procedures.
2. In case of using DIRECT DC-in (without adapter), please check the allowed range for voltage & current of cables. And make sure you have the safety protection for outer issues such as short/broken circuit, overvoltage, surge, lightning strike.
3. In case of using DC-out to an external device, please make sure its voltage and current comply with the motherboard specification.
4. The total power consumption is determined by various conditions (CPU/motherboard type, device, application, etc.). Be cautious to the power cable you use for the system, one with UL standard will be highly recommended.
5. It's highly possible to burn out the CPU if you change/ modify any parts of the CPU cooler.
6. Please wear wrist strap and attach it to a metal part of the system unit before handling a component. You can also touch an object which is ground connected or attached with metal surface if you don't have wrist strap.
7. Please be careful to handle & don't touch the sharp-pointed components on the bottom of PCBA.
8. Remove or change any components from the motherboard will VOID the warranty of the motherboard.
9. Before you install/remove any components or even make any jumper setting on the motherboard, please make sure to disconnect the power supply first. (follow the aforementioned instruction guide)
10. "POWERON after PWR-Fail" function must be used carefully as below:
When the DC power adaptor runs out of power, unplug it from the DC current;
Once power returns, plug it back after 5 seconds.
If there is a power outage, unplug it from the AC current, once power returns, plug it back after 30 seconds. Otherwise it will cause system locked or made a severe damage.

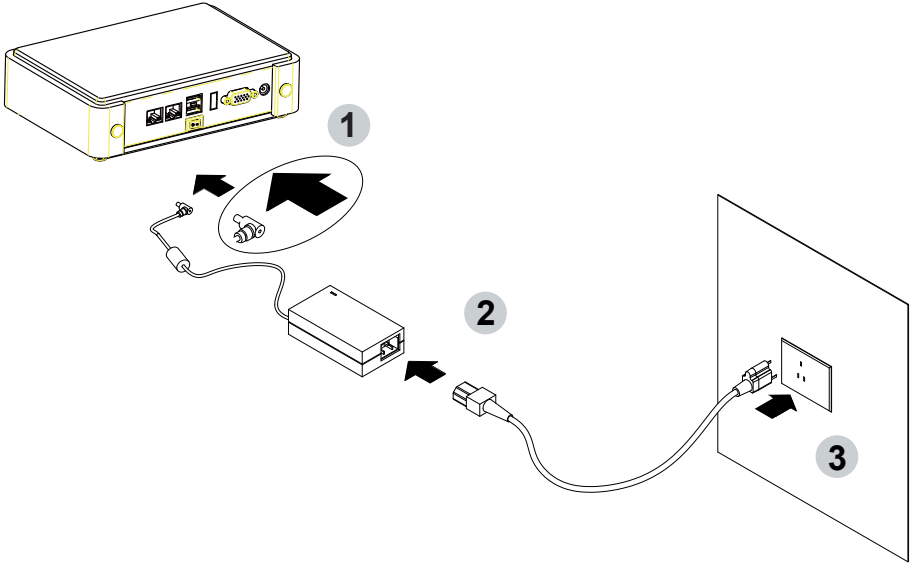
Remark 1:

Always insert/unplug the DC-in horizontally & directly to/from the motherboard. DO NOT twist, it is designed to fit snugly.

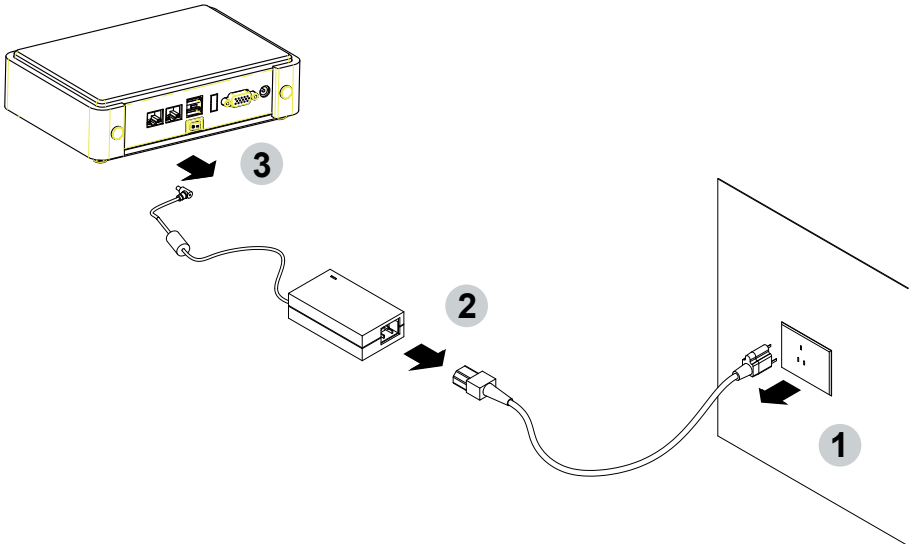
Moreover, erratic pull / push action might cause an unpredictable damage to the component & system unit.

Photo 1

Insert



Unplug



Chapter-1

General Information

The 2I385A/CW is a 2.5 inches form factor All-In-One Board. The board design combines all necessary input and output interfaces, which makes itself an ideal all-in-one control board for POS, Digital Signage and Automation application. Due to its compact size, 2I385A/CW is also the perfect platform for a whole range of small form factor and low-power devices, such as mobile PC or small panel PC

The 2I385A/CW All-In-One motherboard is with Intel BayTrail-I E3815 1.46GHz / E3845 1.91GHz / E3825 1.33 GHz CPU / BayTrail-D J1900 2.0GHz (Single / Quad / Dual core processor), Intel BayTrail E3815 / E3845 / E3825 / J1900 chipset and BayTrail-I / BayTrail-D, Integrated Graphics chipset. This integrated platform offers superb performance and PC specification in the industry. Despite the limited space of 2I385A/CW, it supports 4 COM ports and 4 ports of Hi-Speed USB 2.0 to enhance the host controller interface which will ensure the high performance level and flexible expansion.

The 2I385A/CW supports two LAN ports of 10 / 100 / 1G Ethernet for various and seamless broadband connectivity. With Wake-On LAN function and the PXE function in BIOS, these are perfect control boards for networking devices. The built-in LAN is Intel I211AT LAN chipset for PCIe x 1 V2.1 interface, integrated 10 / 100 / 1000 transceiver.

The 2I385A/CW motherboard is built in with onboard DDR3L SDRAM 2GB / 4GB, J1900 / E3815 / E3845 / E3825 Memory DDR3 data transfer rate of 1066MT/s / 1333MT/s. The expendable interfaces include one full size PCIe Mini card for PCIe and USB interface, one half size PCIe Mini card for mSATA and USB interface.

The supported display interfaces include VGA and LVDS touch screen. The board has a small footprint of only 102 x 73 mm (2.5 inch) and advanced performance in both computing and graphics.

The All-In-One motherboard 2I385A/CW is fully compatible with industrial standards, plus technical enhancements and thousands of software applications developed for IBM PC/AT compatible computers. These control logic provides high-speed performance for the most advanced multi user and multitasking applications available today.

1-1 Major Feature

1. Intel BayTrail-I E3815 1.46GHz / E3845 1.91GHz / E3825 1.33 GHz SOC,
Intel BayTrail-D J1900 2.0 GHz (Quad Core)
(Single / Quad core / Dual Core)
2. Intel BayTrail-I / BayTrail-D Integrated Graphics chipset,
E3815 400 MHz / E3845 542 MHz / E3825 533 MHz render clock frequency
3. On board DDR3L SDRAM 2GB / 4GB Memory,
data transfer rate of 1066MT/s / 1333MT/s
4. Support 2 x 10 / 100 / 1000 Mbps Intel LAN ports
5. Support 4 x COM ports and 4 x USB 2.0
6. Support extended 2 x Mini PCIe card (full size & half size)
7. Support one SATA connector with independent DMA operation supported
8. Hardware digital Input & Output, 4 x DI / 4 x DO
Hardware Watch Dog Timer, 0~255 sec programmable
9. DC +12V Input (2I385A) or Wide range DC input from +9V to +36V ($\pm 1V$) (2I385CW)
10. PCB Dimension: 102 x 73 mm (2.5 inch)
11. Display interfaces include VGA & LVDS (24/48 bits)
12. USB interface Touch screen controller, support 4-, 5-, 8-
wire Analog Resistive touch screen. Resolution is up to 2048 x 2048

1-2 Specification

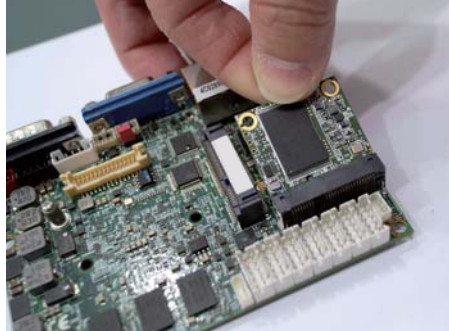
1. **SOC:** Intel BayTrail-I E3815 1.46GHz / E3845 1.91GHz / E3825 1.33GHz, Intel BayTrail-D J1900 2.0 GHz (Quad Core)
(Single / Quad / Dual core)
2. **Memory:** DDR3L SDRAM 2GB / 4GB Memory, data transfer rate of 1066MT/s / 1333MT/s
3. **Graphics:** Intel BayTrail-I / BayTrail-D Integrated Graphics chipset, E3815 400 MHz / E3845 542 MHz / E3825 533MHz / J1900 688MHz render clock frequency
4. **SATA:** One SATA connector with independent DMA operation supported
5. **LAN:** 2 x INTEL I211-AT / I210-IT (option) PCIE LAN of 10 / 100 / 1000 Mbps
6. **Serial Port:** External x 1 (RS232 or 422 or 485); internal x 3 (COM RS232 or 485)
7. **USB:** 4 x USB 2.0 (2 external + 2 internal)
8. **Sound:** ALC886 HD Audio Specification 1.0 Two channel sound chipset
9. **Audio Amplifier:** TPA2011D1 Class-D 2.5W/4Ω or 1.5W/8Ω chipset (2I385C)
10. **WDT/DIO:** Hardware digital Input & Output, 4 x DI / 4 x DO
Hardware Watch Dog Timer, 0~255 sec programmable (2I385C)
11. **Expansion interface:** one full size PCIe Mini card for PCIe and USB interface, one half size PCIe Mini card for mSATA and USB interface
12. **BIOS:** Insyde UEFI BIOS
13. **Dimension:** 102 x 73 mm (2.5 inch)
14. **Power:** DC +12V Input (2I385A) or
Wide range DC input from +9V to +36V (±1V) (2I385CW)
15. **LVDS:** 24 / 48 bits
16. **Touch function:** C8051F321 USB interface Touch screen controller, support 4-, 5-, 8- wire Analog Resistive touch screen.
Resolution is up to 2048 x 2048

1-3 Installing the Mini PCI-e Card

1. Unfasten the round-headed M2*6 screw for half size Mini PCI-e.



2. Install a mSATA card at the angle of 45°.
(The half size Mini PCI-e slot supports mSATA)



3. Fasten a round-headed M2*6 screw.

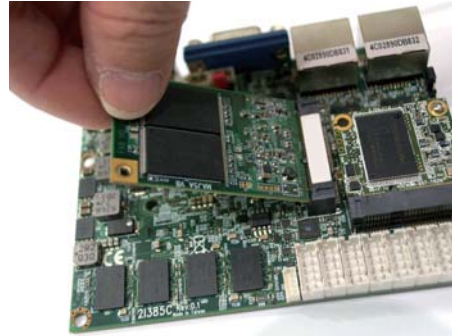


1-4 Directions for installing the Mini Card

1. Unscrew the screw on the board



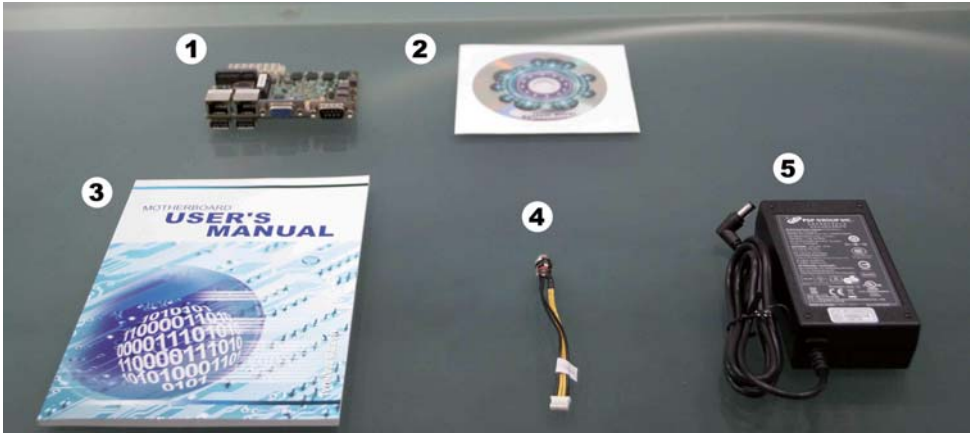
2. Plug in the Mini Card in a 45 angle



3. Gently push down the Mini Card and screw the screw back.



1-5 Packing List



	Material Code	Description	Detail Specification	Quantity
1	7G1901-1500001-0	MB-2I385A-I44-001	LF,2I385A-I44,Rev.:001	1
2	6G8006-2347-0100	LEX Product Driver DVD	LF, Intel Baytrail Driver	1
3	6G8001-2192-0400	Manual	LF,M/B,2I385A/C	1
4	6G6003-7330-0100	Power Cable	LF,L=9cm,2.0 1*4/DC JK	1
5	6G5212-0301-0300	30W Power Adapter,12V/2.5A	LF,L Type,EA10301-M06,EDAC	1

**Optional accessories (items in addition to motherboard)
are not included in the standard packing.
Please contact your dealer to purchase the optional accessories.**

Chapter-2

Hardware Installation

2-1 Unpacking Precaution

This chapter provides the information how to install the hardware of 2I385A/2I385CW. Please follow section 1-5, 2-1 and 2-2 to check the delivery package and unpack carefully. Please follow the jumper setting procedure.

NOTE!

1. Do not touch the board or any other sensitive components without all necessary anti-static protection.
2. Please pay attention to the voltage limitation of DC-IN 12V 5%.
Overuse of DC-IN voltage limitation or change to another power adapter (not provided with this system) will VOID warranty.

You should follow these steps to protect the board from the static electric discharge whenever you handle the board:

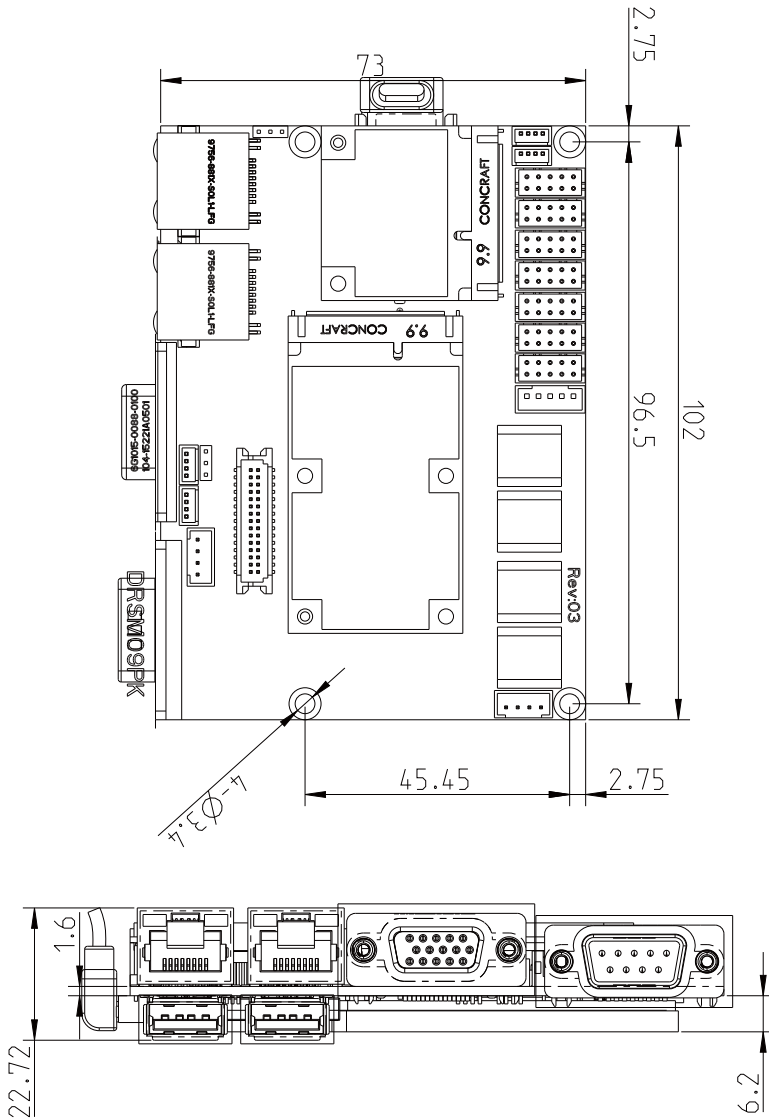
1. Ground yourself by a grounded wrist strap at all times when you handle the 2I385A/2I385CW.
Well secure the ALLIGATOR clip of the strap to the end of the shielded wire lead from a grounded object. Please put on and connect the strap before handling the 2I385A/2I385CW for harmlessly discharge any static electricity through the strap.
2. Please use anti-static pad to put any components, parts, or tools on the pad whenever you work on them outside the computer. You may also use the anti-static bag instead of the pad. Please ask your local supplier for necessary parts on anti-static requirement.
3. Do not plug any connector or set any jumper when the power is on.

2-2 Unpacking checkup

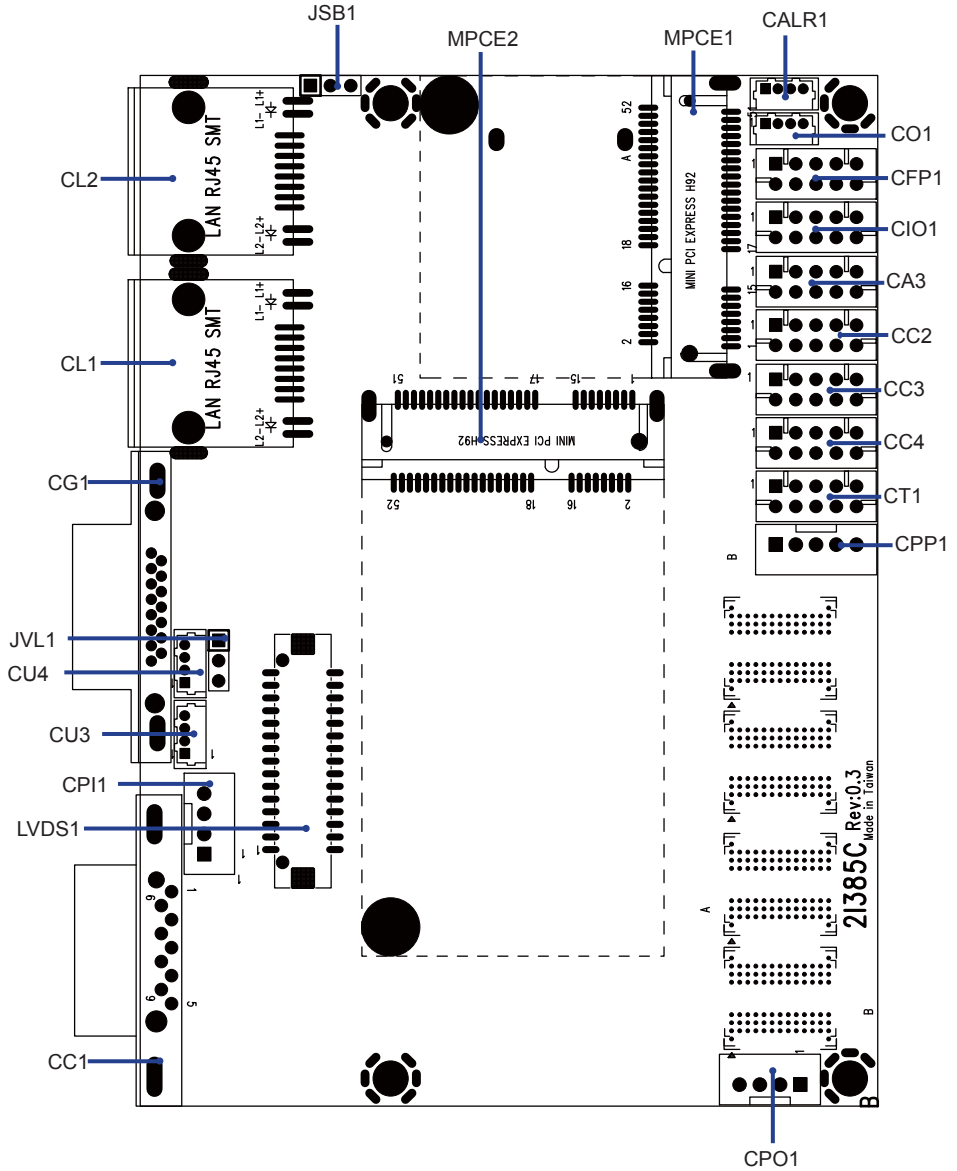
First of all, please follow all necessary steps of section 2-1 to protect 2I385A/2I385CW from electricity discharge. With reference to section 1-5 please check the delivery package again with following steps:

1. Unpack the 2I385A/2I385CW board and keep all packing material, manual and driver disc etc, do not dispose !
2. Is there any components lose or drops from the board?
DO NOT CONTINUE TO INSTALL THIS BOARD!
CONTACT THE DEALER YOU PURCHASED THIS BOARD FROM, IMMEDIATELY.
3. Is there any visible damage on the board?
DO NOT CONTINUE TO INSTALL THIS BOARD!CONTACT THE DEALER YOU PURCHASED THIS BOARD FROM, IMMEDIATELY.
4. Check your optional parts (i.e. DDR, CF etc.), all necessary jumpers setting to jumper pin-set, and CMOS setup correctly.
Please also refer to all information of jumper settings in this manual.
5. Check your external devices (i.e. Add-On-Card, Driver Type etc.) for complete add-in or connection and CMOS setup correctly.
Please also refer to all information of connector connection in this manual.
6. Please keep all necessary manual and driver disc in a good condition for future re-installation if you change your Operating System.

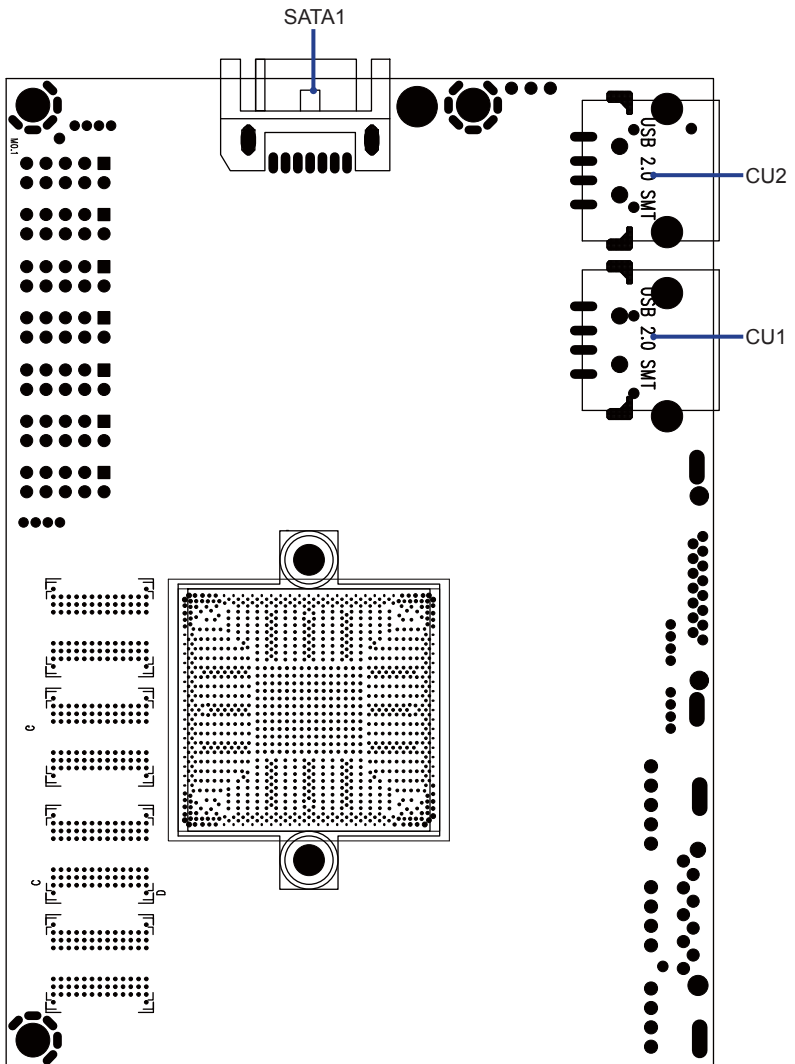
2-3 Dimension-2I385A/2I385CW



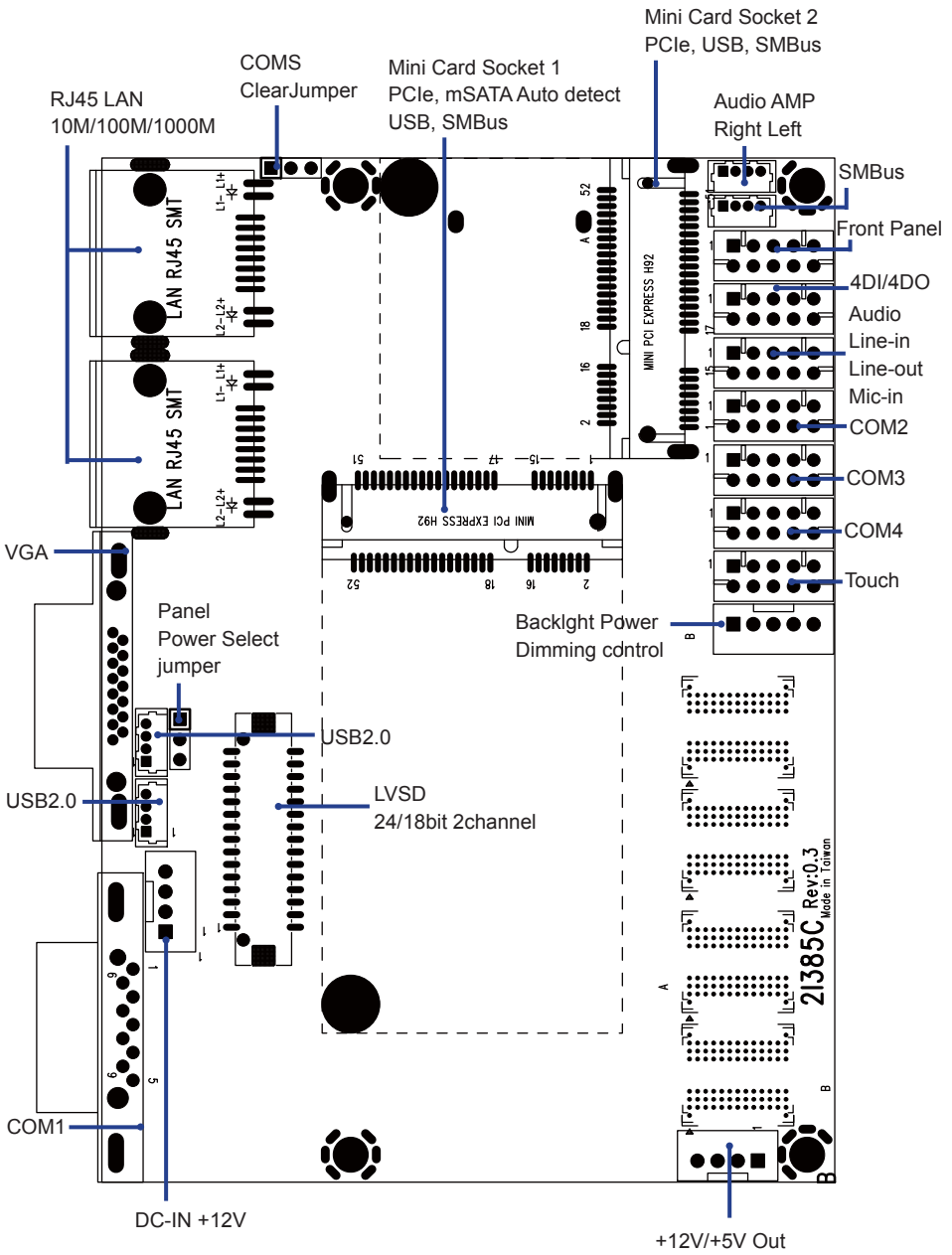
2-4 Layout-2I385A/2I385CW-Connector and Jumper



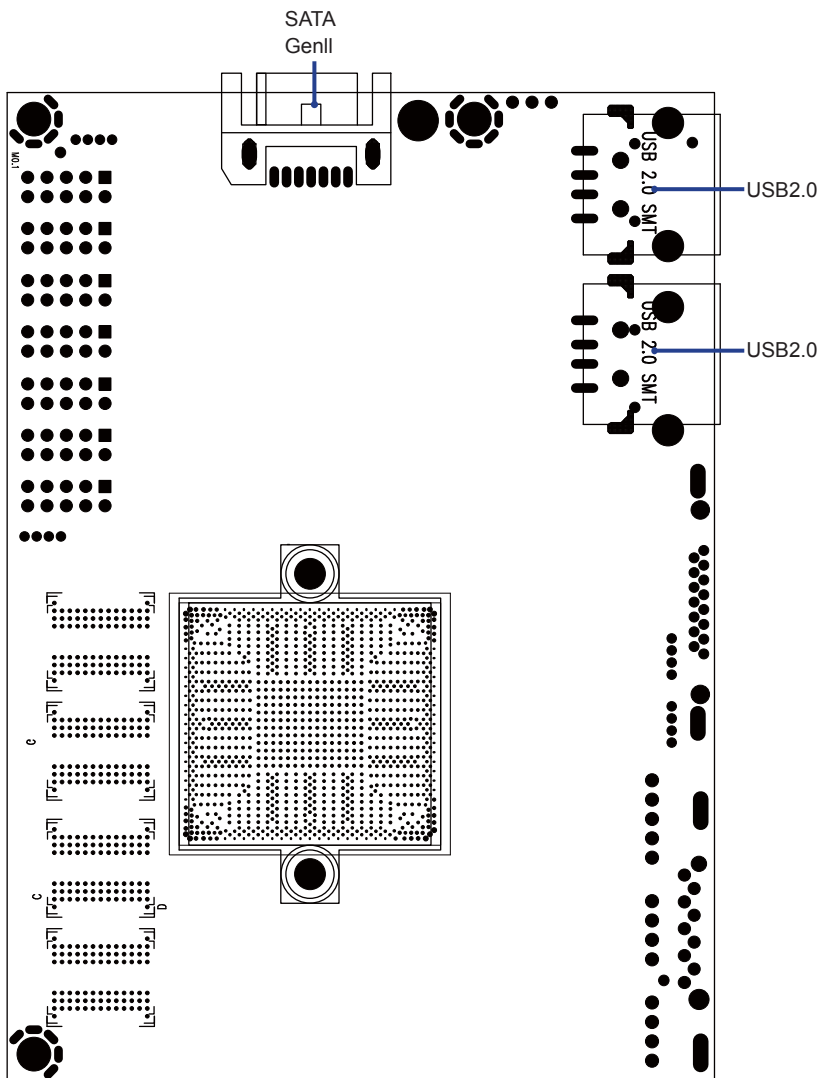
2-4-1 Layout-2I385A/2I385CW-Connector and Jumper Bottom



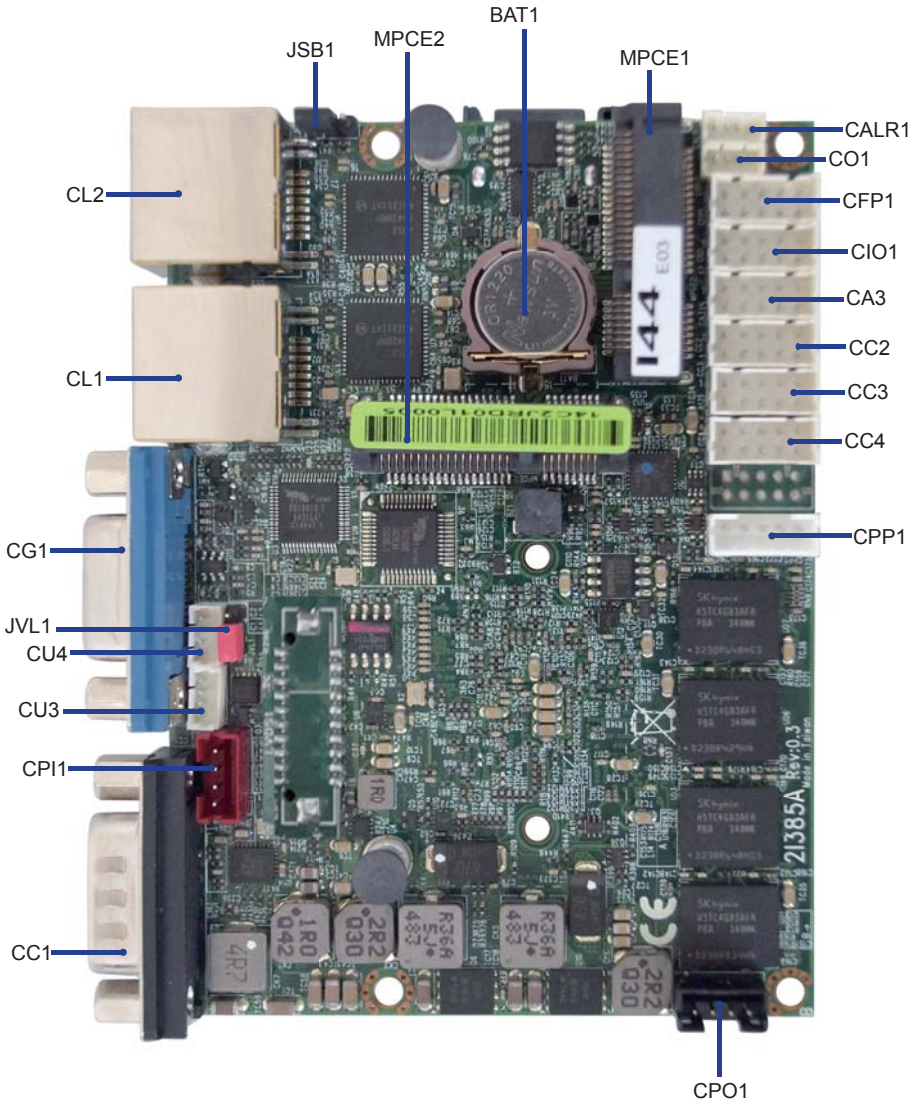
2-4-2 Layout-2I385A/2I385CW-Function MAP



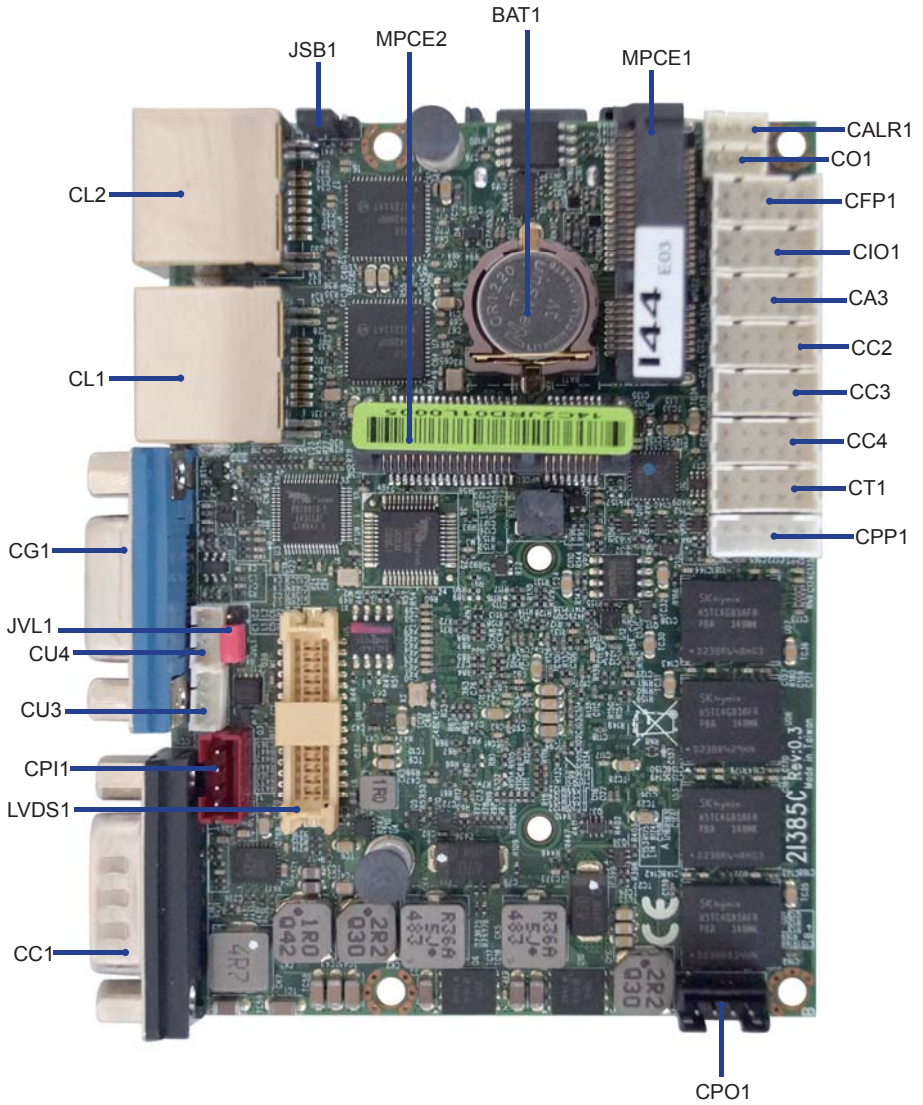
2-4-3 Layout-2I385A/2I385CW-Function MAP Bottom



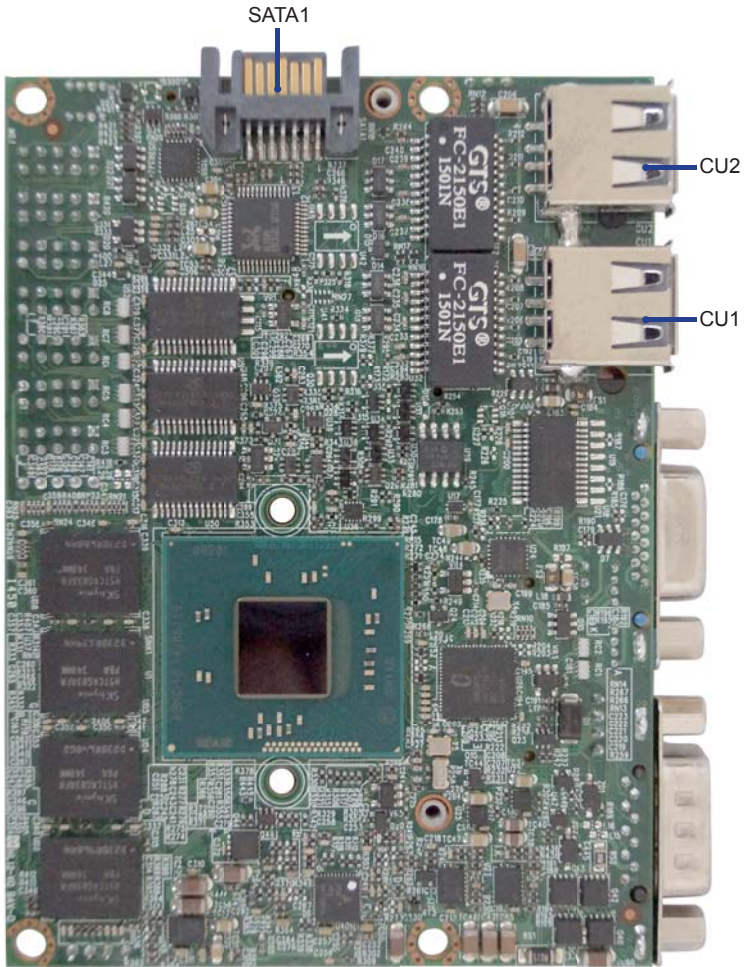
2-5 Diagram- 2I385A



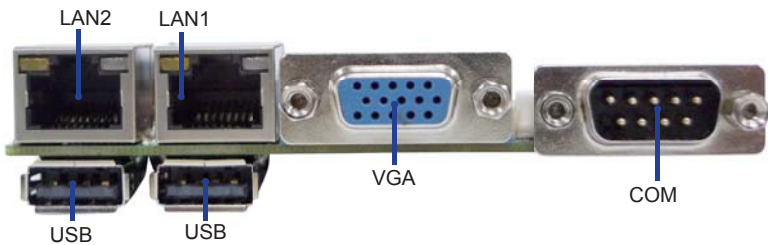
2-5-1 Diagram- 2I385CW



2-5-2 Bottom Side Diagram- 2I385A/2I385CW



BACK Panel



2-6 List of Jumpers

JSB1: CMOS DATA clear

JVL1: LCD Panel power select

2-7 Jumper Setting Description

A jumper is ON as a closed circuit with a plastic cap covering two pins. A jumper is OFF as an open circuit without the plastic cap. Some jumpers have three pins, labeled 1, 2, and 3. You could connect either pin 1 and 2 or 2 and 3.

The below figure 2.2 shows the examples of different jumper settings in this manual.

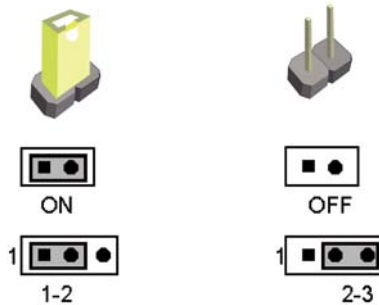


Figure 2.2

All jumpers already have its default setting with the plastic cap inserted as ON, or without the plastic cap as OFF. The default setting may be referred in this manual with a " * " symbol .

2-8 JSB1: CMOS Data Clear

A battery must be used to retain the motherboard configuration in CMOS RAM. Close Pin1 and Pin2 of JSB1 to store the CMOS data.

To clear the CMOS, follow the procedures below:

1. Turn off the system and unplug the AC power
2. Remove DC 12V power cable from DC 12V power connector
3. Locate JSB1 and close pin 1-2 for few seconds
4. Return to default setting by close pin 1-2
5. Connect DC 12V power cable back to DC 12V Power connector

JSB1	Description
*1-2	Normal set
2-3	CMOS data clear

Note: Do not clear CMOS unless

- 1. Troubleshooting**
- 2. Forget password**
- 3. You fail over-clocking system**

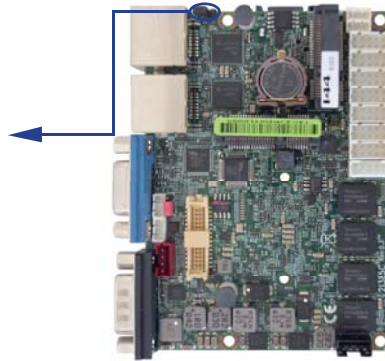
JSB1



*Normal



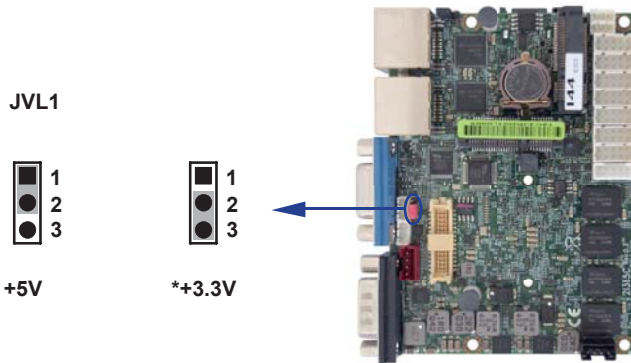
COMS



2-9 JVL1: LCD panel power select

JVL1	Description
1-2	+5V
*2-3	+3.3V

Note: Attention! Check Device Power in spec.



Chapter-3

Connection

This chapter provides all necessary information of the peripheral's connections, switches and indicators. Always power off the board before you install the peripherals.

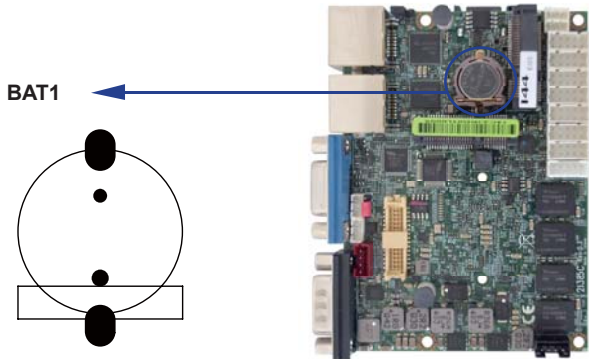
3-1 List of Connectors

BAT1:	Li 3V battery holder
CA3:	Line-out / Line-in / Mic-in / SPDIF-out 2x5 pin (2.0mm) Wafer
CALR1:	Amplifier Line-out Right / Left channel 4pin (1.25mm) wafer
CC1 :	COM1 DB9 Connector
CC2 :	COM 2x5pin (2.0mm) wafer
CC3 :	COM 2x5pin (2.0mm) wafer
CC4 :	COM 2x5pin (2.0mm) wafer
CFP1:	Front Panel connector 2x5pin (2.0mm) wafer
CG1:	VGA DB15 Connector
CIO1:	DIO 2x5 pin (2.0mm) Wafer
CL1 :	LAN port 1 RJ45 Connector
CL2 :	LAN port 2 RJ45 Connector
CL11 :	LAN port 1 RJ45 2x4 pin (2.0mm) wafer(option)
CL21 :	LAN port 2 RJ45 2x4 pin (2.0mm) wafer(option)
CO1:	SMBus 4pin (1.25mm) Wafer
CPI1:	DC 12V-IN 1x4 pin (2.0mm) Red wafer connector
CPP1:	Panel inverter power connector 1x5 pin (2.0mm) wafer
CPO1:	+12V / +5V power output 4 pin (2.0mm) Black wafer connector
CT1:	Touch screen device 2x5 pin (2.0mm) Wafer
CU1:	USB 2.0 Dual port Type A connector
CU2:	USB 2.0 Dual port Type A connector
CU3:	USB 2.0 port 4pin (1.25mm) Wafer
CU4:	USB 2.0 port 4pin (1.25mm) Wafer
LVDS1:	LVDS 2x15 pin (1.25mm) connector
SATA1:	One SATA connector 7pin
MPCE1 :	Full size mini card port 1 sockets 52pin
MPCE2 :	Half size mini card port 2 sockets 52pin

3-2 CMOS Battery connector

- **BAT1: 3V Battery hold 2pin**
BAT1: Battery use Li 3V / 40mAh (CR1220)

Note : 1. When board without Adaptor plug in, this board power RTC consumption 2.7uA
2. If adaptor always plug in RTC power consumption 0.1uA



3-3 Audio interface

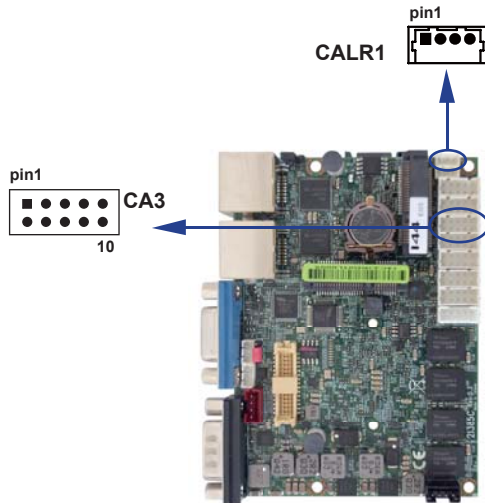
● **CA3: Line-out / Line-in / Mic-in / SPDIF-out 2x5 pin (2.0mm) Wafer**

PIN NO.	Description	PIN NO.	Description
1	Line-out-R	2	MIC-IN
3	Line-in-R	4	GND
5	GND	6	SPDIF-OUT
7	Line-in-L	8	+5V
9	Line-out-L	10	MIC-IN

3-4 Audio Amplifier

● **CALR1: Amplifier Line-out Right / Left channel 4pin (1.25mm) wafer**

PIN NO.	Description
1	Left+
2	Left-
3	Right-
4	Right+



3-5 COM interface

● CC1 COM1 DB9 Connector (RS232 Mode)

PIN NO.	Description	PIN NO.	Description
1	DCD	6	DSR
2	RXD	7	RTS
3	TXD	8	CTS
4	DTR	9	RI / Voltage
5	GND		

Note:

The pin9 RI can be modify to Power to supply device. The power voltage can be set +12V or +5V. The RI change Voltage function is OEM need change BOM. Default is RI signal.

● CC1 COM1 DB9 Connector (RS485 Mode)

PIN NO.	Description	PIN NO.	Description
1	RS485 Data+	6	NC
2	RS485 Data-	7	NC
3	NC	8	NC
4	NC	9	NC
5	GND		

Note : 1. Default BOM set to RS232 Mode
2. RS485 function for OEM BOM request

● CC1 COM1 DB9 Connector (RS422 Mode)

PIN NO.	Description	PIN NO.	Description
1	RS422 TX-	6	NC
2	RS422 TX+	7	NC
3	RS422 RX+	8	NC
4	RS422 RX-	9	NC
5	GND		

Note : 1. Default BOM set to RS232 Mode
2. RS422 function for OEM BOM request



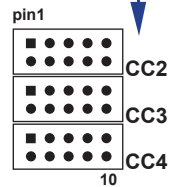
● **CC2/3/4 COM2/3/4 2x5pin (2.0mm) wafer (RS232 Mode)**

PIN NO.	Description	PIN NO.	Description
1	DCD	2	RXD
3	TXD	4	DTR
5	GND	6	DSR
7	RTS	8	CTS
9	RI	10	+5V



● **CC2/3/4 COM2/3/4 2x5pin (2.0mm) wafer (RS485 Mode)**

PIN NO.	Description	PIN NO.	Description
1	RS485 Data-	2	RS485 Data+
3	NC	4	NC
5	GND	6	NC
7	NC	8	NC
9	NC	10	+5V



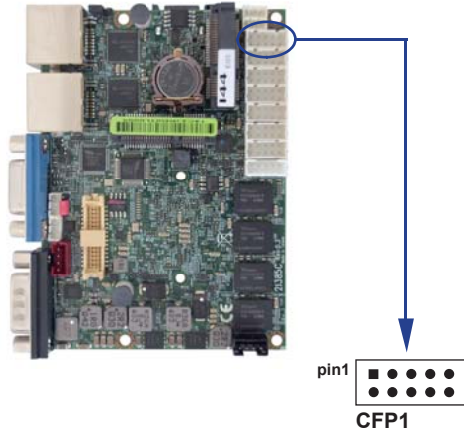
Note:

1. CC2 / CC3 / CC4 connector RS485 function for OEM BOM request
2. BIOS need setting to RS485 mode

3-6 Front Panel Pin Header

• CFP1 Front Panel connector 2x5pin (2.0mm) wafer

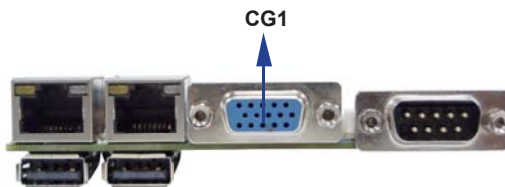
PIN NO.	Description	PIN NO.	Description
1	Power button pin	2	Power button GND
3	Reset pin	4	Reset GND
5	Power LED-	6	Power LED+
7	HDD LED-	8	HDD LED+
9	LAN LED-	10	LAN LED+



3-7 VGA Display interface

• CG1: VGA Connector (DB15 pin)

PIN NO.	Description	PIN NO.	Description	PIN NO.	Description
1	RED	6	GND	11	NC
2	GREEN	7	GND	12	DDC DATA
3	BLUE	8	GND	13	H-SYNC
4	NC	9	NC	14	V-SYNC
5	GND	10	GND	15	DDC CLOCK

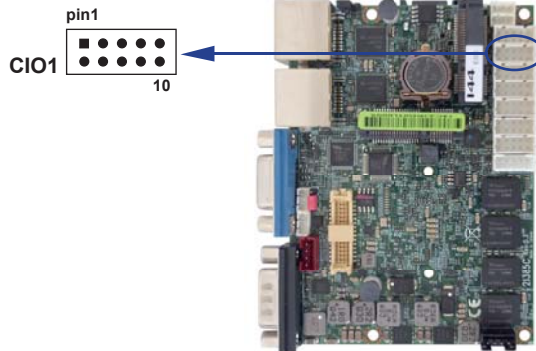


3-8 Digital Input / Output / Watch Dog Time

- CIO1 DIO 0-3 (2x5pin 2.0mm wafer)

PIN NO.	Description	PIN NO.	Description
1	DI-0	2	DO-3
3	DI-1	4	DO-2
5	DI-2	6	DO-1
7	DI-3	8	DO-0
9	GND	10	+5V

- Note: 1. DI pin default pull up 10K Ω to +5V
2. If use need isolate circuit to control external device
3. F75111N-1 SMBus address 0x9c



- For F75111N SMBus watch dog timer device:

DC spec:

Input low Voltage (VIL): +0.8 Max,

Input High Voltage (VIH): +2V Min

Output low Current (IOL): 10mA (Min) VOL=0.4V

Output High Current (IOH): -10mA (Min) VOL=2.4V

Watch Dog Time value 0~255 sec

The system will be issued reset. When WDT is enable the hardware start down counter to zero. The reset timer have 10~20% tolerance upon the Temperature.

Note: If want to SDK support. Please contact to sales window.

3-8-1 IO Device: F75111 CIO Utility

The Sample code source you can download from

http://tprd.info/lexwiki/index.php/IO_Device:F75111_CIO_Utility

<Google Drive>

Source file: CIO_Utility_v3.0.7.2W_Src

Binary file: CIO_Utility_v3.0.7.2W_Bin_x86 CIO_Utility_v3.0.7.2W_Bin_x64

F75113 DLL: F75113.zip

<FTP>

Source file: CIO_Utility_v3.0.7.2W_Src

Binary file: CIO_Utility_v3.0.7.2W_Bin_x86 CIO_Utility_v3.0.7.2W_Bin_x64

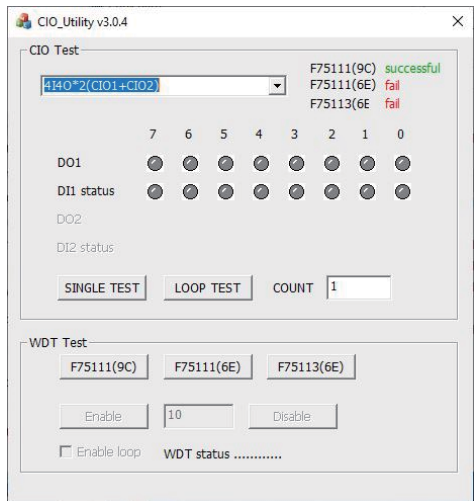
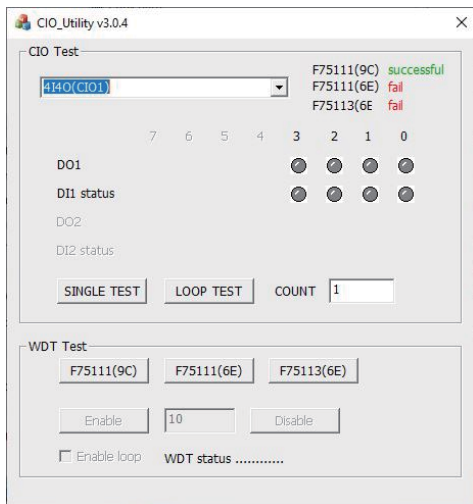
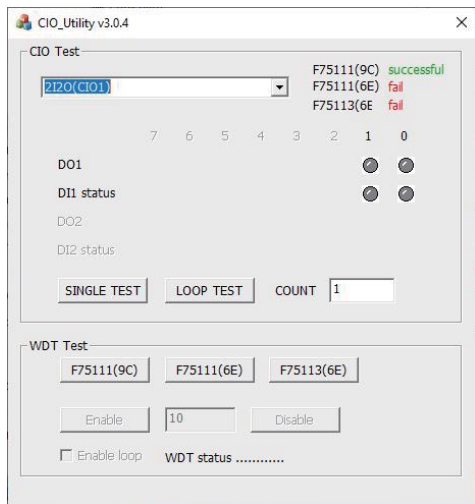
F75113 DLL: F75113.zip

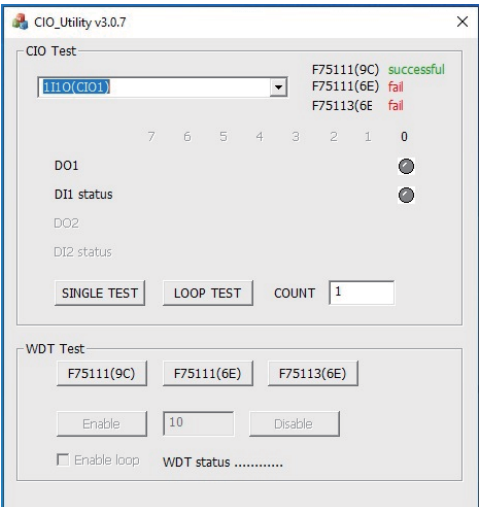
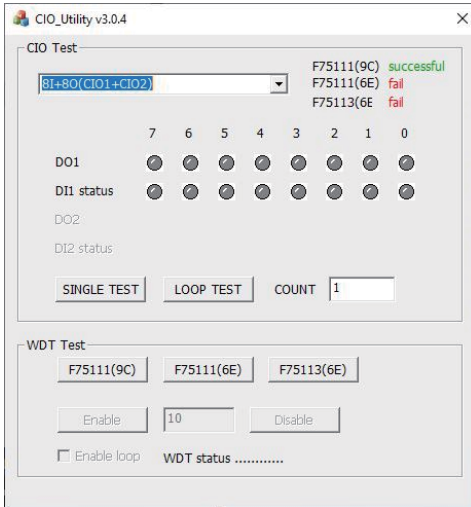
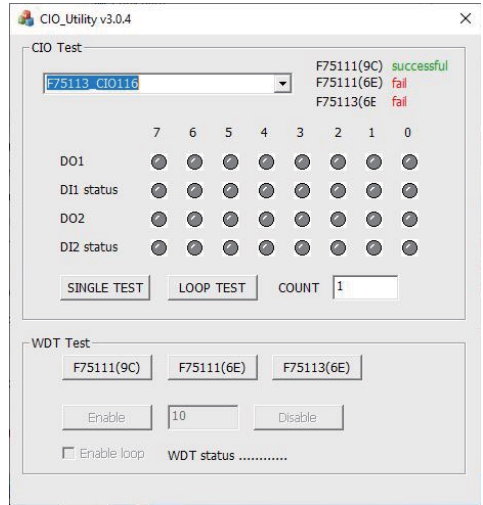
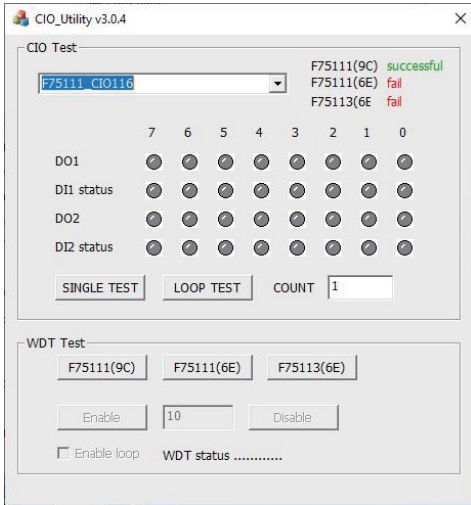
MB Support List

Ivybridge	Bay Trail	Apollo Lake	Skylake / Kabylake
2I847H 3I847A/D/CW/ NX/NM/HW 3I770A/CW CI847A/C CI770A/C	1I385A/H 1I386H 2I380A 2I385A/CW 2I380NX 2I385BW/EW/HW/PW 2I386EW 2I382A 2I382DW 3I380A/CW/NX ST385W/AW/CW	2I390CW 2I392CW 3I390AW 3I390NX 3I393NX PM390C	2I610DW/HW 2I612CW 3I610DW 3I612DW 3I170DW/HW/NX ST610W CI170A/C PM610DW PM170DW

Coffee Lake	Whiskey Lake	AMD	Card	Elkhart Lake
CI370DW	2I810D 3I810DW	3A100DW	CIO116-G E691A	2I640DW

How to use this Demo Application

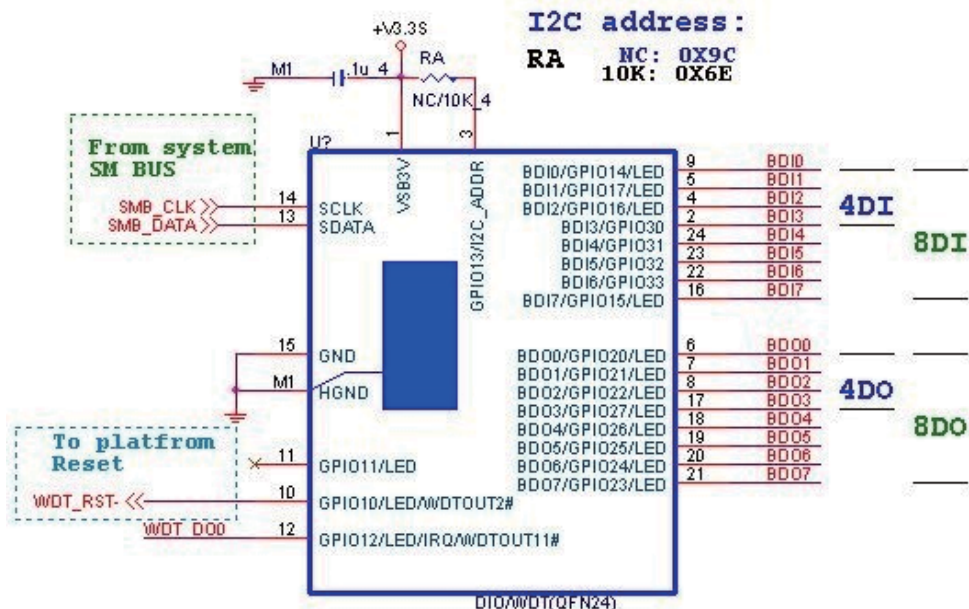




Attention Please: You must be install vcredist_x86.exe when first time you run the F75111_DIO.exe DEMO AP, The vcredist_x86.exe include all required DLL file.

1. Press the select your test "2i2o", "4i4o", "4i4o*2", "F75111CIO116", "F75113CIO116", "8i+8o", "1i1o"
2. start test, select single mode or looptest

F75111 Layout Picture



Introduction F75111

Initial Internal F75111 port address (0x9c)

define GPIO1X, GPIO2X, GPIO3X to input or output
and Enable WDT function pin

Set F75111 DI/DO (sample code as below Get Input value/Set output value)

DO: InterDigitalOutput(BYTE byteValue))
DI: InterDigitalInput()

PULSE mode

Sample to setting GP33, 32, 31, 30 output 1mS low pulse signal.

```
{
this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_PULSE_CONTROL,           0x00);
// This is setting low,Level output
this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_PULSE_WIDTH_CONTROL,    0x01);
// This selects the pulse width to 1mS
this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_CONTROL_MODE,           0x0F);
// This is setting the GP33, 32, 31, 30 to output function.
this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_Output_Data ,           0x0F);
// This is setting the GP33, 32, 31, 30 output data.
}
```

Initial internal F75111

```
void F75111::InitInternalF75111()
{
this->Write_Byte(F75111_INTERNAL_ADDR,GPIO1X_CONTROL_MODE,           0x00)
; //set GPIO1X to Input function
this->Write_Byte(F75111_INTERNAL_ADDR,GPIO3X_CONTROL_MODE,           0x00)
; //set GPIO3X to Input function
this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_CONTROL_MODE,           0xFF)
; //set GPIO2X to Output function
this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_OUTPUT_DRIVING,         0xFF)
; //set GPIO2X to Output Drving

this->Write_Byte(F75111_INTERNAL_ADDR,F75111_CONFIGURATION, 0x03);
//Enable WDT OUT function
}
```

Set output value

```
void F75111::InterDigitalOutput(BYTE byteValue)
{
BYTE byteData = 0;
byteData = (byteData & 0x01)? byteValue + 0x01 : byteValue;
byteData = (byteData & 0x02)? byteValue + 0x02 : byteValue;
byteData = (byteData & 0x04)? byteValue + 0x04 : byteValue;
byteData = (byteData & 0x08)? byteValue + 0x08 : byteValue;
byteData = (byteData & 0x10)? byteValue + 0x10 : byteValue;
byteData = (byteData & 0x20)? byteValue + 0x20 : byteValue;
byteData = (byteData & 0x40)? byteValue + 0x40 : byteValue;
byteData = (byteData & 0x80)? byteValue + 0x80 : byteValue;           // get value bit by bit

this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_OUTPUT_DATA,byteData);
// write byteData value via GPIO2X output pin
}
```

Get Input value

```
BYTE F75111::InterDigitalInput()
{
  BYTE byteGPIO1X = 0;
  BYTE byteGPIO3X = 0;
  BYTE byteData = 0;

  this->Read_Byte(F75111_INTERNAL_ADDR,GPIO1X_INPUT_DATA,&byteGPIO1X) ;
  // Get value from GPIO1X
  this->Read_Byte(F75111_INTERNAL_ADDR,GPIO3X_INPUT_DATA,&byteGPIO3X) ;
  // Get value from GPIO3X

  byteGPIO1X = byteGPIO1X & 0xF0;           // Mask unuseful value
  byteGPIO3X = byteGPIO3X & 0x0F;         // Mask unuseful value

  byteData = ( byteGPIO1X & 0x10 )? byteData + 0x01 : byteData;
  byteData = ( byteGPIO1X & 0x80 )? byteData + 0x02 : byteData;
  byteData = ( byteGPIO1X & 0x40 )? byteData + 0x04 : byteData;
  byteData = ( byteGPIO3X & 0x01 )? byteData + 0x08 : byteData;

  byteData = ( byteGPIO3X & 0x02 )? byteData + 0x10 : byteData;
  byteData = ( byteGPIO3X & 0x04 )? byteData + 0x20 : byteData;
  byteData = ( byteGPIO3X & 0x08 )? byteData + 0x40 : byteData;
  byteData = ( byteGPIO1X & 0x20 )? byteData + 0x80 : byteData;
  // Get correct DI value from GPIO1X & GPIO3X

  return byteData;
}
```


define F75111 pin in F75111.h

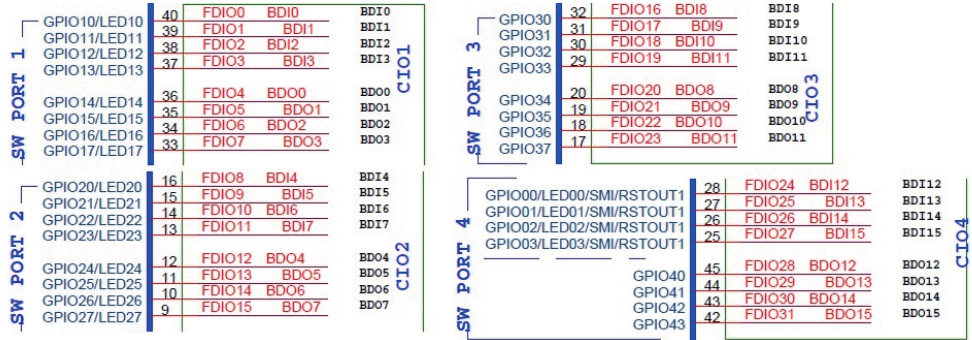
```

//-----
#define F75111_INTERNAL_ADDR      0x9C // OnBoard F75111 Chipset
#define F75111_EXTERNAL_ADDR     0x6E // External F75111 Chipset
//-----
#define F75111_CONFIGURATION      0x03 // Configure GPIO13 to WDT2 Function
//-----
#define GPIO1X_CONTROL_MODE       0x10 // Select Output Mode or Input Mode
#define GPIO2X_CONTROL_MODE       0x20 // Select GPIO2X Output Mode or Input Mode
#define GPIO3X_CONTROL_MODE       0x40 // Select GPIO3X Output Mode or Input Mode
//-----
#define GPIO1X_INPUT_DATA         0x12 // GPIO1X Input Data Register
#define GPIO3X_INPUT_DATA         0x22 // GPIO2X Input Data Register
#define GPIO3X_INPUT_DATA         0x42 // GPIO3X Input Data Register
//-----
#define GPIO1X_OUTPUT_DATA        0x11 // GPIO1X Output Data Register
#define GPIO2X_OUTPUT_DATA        0x21 // GPIO2X Output Data Register
#define GPIO3X_OUTPUT_DATA        0x41 // GPIO3X Output Data Register
//-----
#define GPIO1X_OUTPUT_DRIVING     0x1B // Select GPIO1X Output Driving Enable
#define GPIO2X_OUTPUT_DRIVING     0x2B // Select GPIO2X Output Driving Enable
#define GPIO3X_OUTPUT_DRIVING     0x4B // Select GPIO3X Output Driving Enable
//-----
#define GPIO1X_PULSE_CONTROL      0x13 // GPIO1x Level/Pulse Control Register
// 0:Level Mode
// 1:Pulse Mode
#define GPIO1X_PULSE_WIDTH_CONTROL 0x14 // GPIO1x Pulse Width Control Register
#define GP1_PSWIDTH_500US         0x00 // When select Pulse mode:500 us.
#define GP1_PSWIDTH_1MS           0x01 // When select Pulse mode:1 ms.
#define GP1_PSWIDTH_20MS          0x02 // When select Pulse mode:20 ms.
#define GP1_PSWIDTH_100MS        0x03 // When select Pulse mode:100 ms.
//-----
#define GPIO2X_PULSE_CONTROL      0x23 // GPIO2x Level/Pulse Control Register
// 0:Level Mode
// 1:Pulse Mode
#define GPIO2X_PULSE_WIDTH_CONTROL 0x24 // GPIO2x Pulse Width Control Register
#define GP2_PSWIDTH_500US         0x00 // When select Pulse mode:500 us.
#define GP2_PSWIDTH_1MS           0x01 // When select Pulse mode:1 ms.
#define GP2_PSWIDTH_20MS          0x02 // When select Pulse mode:20 ms.
#define GP2_PSWIDTH_100MS        0x03 // When select Pulse mode:100 ms.
//-----
#define GPIO3X_PULSE_CONTROL      0x43 // GPIO3x Level/Pulse Control Register
// 0:Level Mode
// 1:Pulse Mode
#define GPIO3X_Output_Data        0x41 // GPIO3x Output Data Register
#define GPIO3X_PULSE_WIDTH_CONTROL 0x44 // GPIO3x Pulse Width Control Register
#define GP3_PSWIDTH_500US         0x00 // When select Pulse mode:500 us.
#define GP3_PSWIDTH_1MS           0x01 // When select Pulse mode:1 ms.
#define GP3_PSWIDTH_20MS          0x02 // When select Pulse mode:20 ms.
#define GP3_PSWIDTH_100MS        0x03 // When select Pulse mode:100 ms.
//-----

```

Introduction F75113

F75113 Layout Picture



Base on 75113.DII API function as below list

```

F75113_API bool_stdcall F75113_Init();
F75113_API BYTE
//BDI0-BDI7
F75113_API BYTE
//BDI8-BDI15
F75113_API void
//BDO0-BDO7
F75113_API void
//BDO8-BDO15

F75113_API void
//For the F75113 on board
F75113_API void
//For the F75113 on board

F75113_GetDigital_Low_Input();
F75113_GetDigital_High_Input();
F75113_SetDigital_Low_Output(BYTE byteValue);
F75113_SetDigital_High_Output(BYTE byteValue);
F75113_SetWDT_Enable(BYTE byteTimer);
F75113_SetWDT_Disable();

```

3-8-2 IO Device: F75111 CIO Utility under Linux

http://tprd.info/lexwiki/index.php/IO_Device:F75111_CIO_Utility_under_Linux

The Sample code source you can download from<Google Drive>

Source file: CIO_Utility_v3.2.1L_Src

Binary file: CIO_Utility_v3.2.1L_Bin_x64

<FTP>

Source file: CIO_Utility_v3.2.1L_Src

Binary file: CIO_Utility_v3.2.1L_Bin_x64

MB Support List

Ivybridge	Bay Trail	Apollo Lake	Skylake / Kabylake
21847H 31847A/D/CW /NX/NM/HW 31770A/CW C1847A/C C1770A/C	11385A/H 11386H 21380A 21385A/CW 21380NX 21385BW/EW/HW/PW 21386EW 21382A 21382DW 31380A/CW/NX ST385W/AW/CW	21390CW 21392CW 31390AW 31390NX 31393NX PM390C	21610DW/HW 21612CW 31610DW 31612DW 31170DW/HW/NX ST610W C1170A/C PM610DW PM170DW

Coffee Lake	Whiskey Lake	AMD	Card	Elkhart Lake
C1370DW	21810D 31810DW	3A100DW	C10116-G E691A	21640DW

How to use this Demo Application

CIO_Utility_v3.2

Platform: **AMD**

=====SMBus1(CO1)=====

F75111 F75113

7 6 5 4 3 2 1 0

Digital Output 1

Digital Input 1

Digital Output 2

Digital Input 2

Start test

F75111(9C) F75113(6E)

WDT test Enable 10 Disable Enable Loop Test

Status_test

SMBUS1(CO1)

F75111(9C) N/A

F75111(6E) N/A

F75113(6E) N/A

SMBUS2(CO2)

F75111(6E) **Sessuce**

F75113(6E) **Fail**

CIO_Utility_v3.2

Platform: **AMD**

=====SMBus2(CO2)=====

F75111 F75113

7 6 5 4 3 2 1 0

Digital Output 1

Digital Input 1

Digital Output 2

Digital Input 2

Start test

F75111(9C) F75113(6E)

WDT test Enable 10 Disable Enable Loop Test

Status_test

SMBUS1(CO1)

F75111(9C) N/A

F75111(6E) N/A

F75113(6E) N/A

SMBUS2(CO2)

F75111(6E) **Sessuce**

F75113(6E) **Fail**

CIO_Utility_v3.2

Platform: **AMD**

1110

F75111 F75113

7 6 5 4 3 2 1 0

Digital Output 1

Digital Input 1

Digital Output 2

Digital Input 2

Start test

F75111(9C) F75113(6E)

WDT test Enable 10 Disable Enable Loop Test

Status_test

SMBUS1(CO1)

F75111(9C) N/A

F75111(6E) N/A

F75113(6E) N/A

SMBUS2(CO2)

F75111(6E) **Sessuce**

F75113(6E) **Fail**

CIO_Utility_v3.2

Platform: **AMD**

2120

F75111 F75113

7 6 5 4 3 2 1 0

Digital Output 1

Digital Input 1

Digital Output 2

Digital Input 2

Start test

F75111(9C) F75113(6E)

WDT test Enable 10 Disable Enable Loop Test

Status_test

SMBUS1(CO1)

F75111(9C) N/A

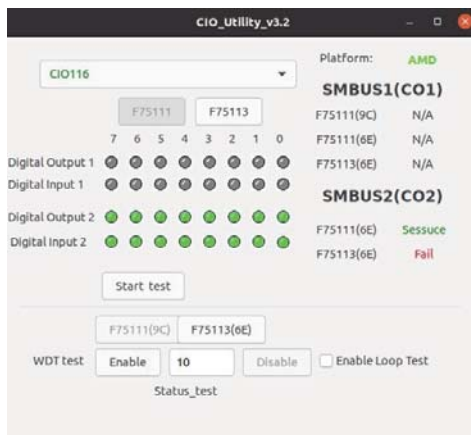
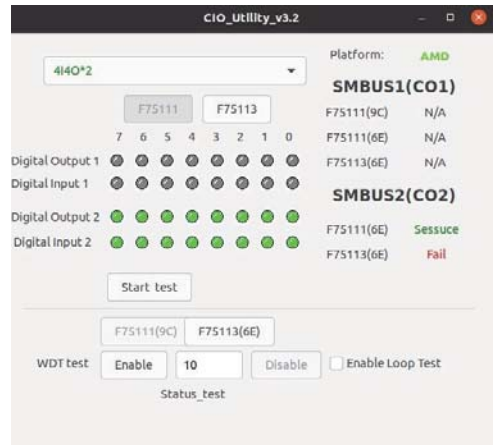
F75111(6E) N/A

F75113(6E) N/A

SMBUS2(CO2)

F75111(6E) **Sessuce**

F75113(6E) **Fail**



Before executing the program began, Please switch to the highest authority , continued second F75111 ,chmod 777 and root: \

Platform will detect intel/AMD , if not get SMBus signal show N/A

If get SMBUS1 / SMBUS2 F75111 / F75113 will show Sessuce, IC not get will show Fail,

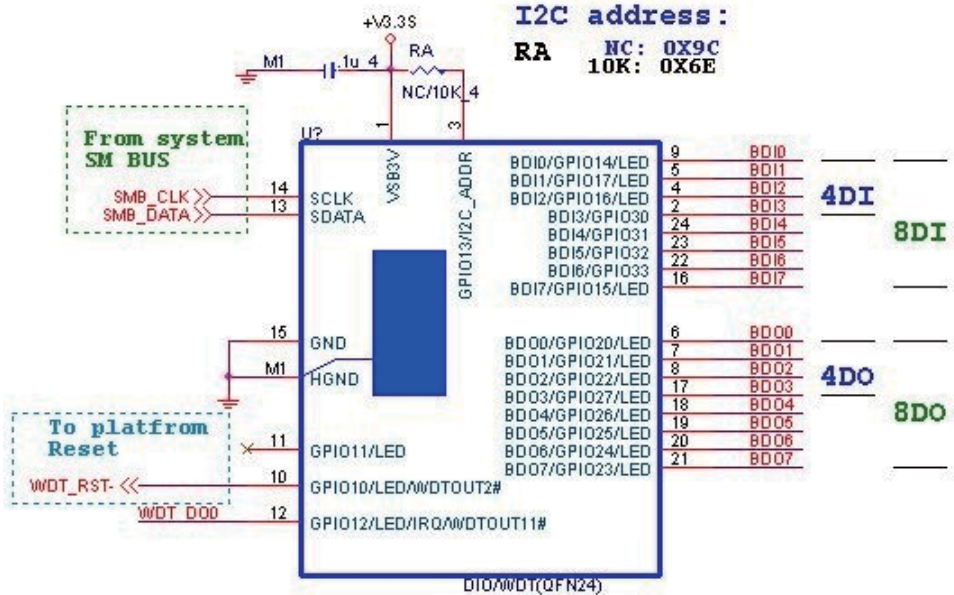
Not get SMBUS1 / SMBUS2 signal will show N/A

1. Press the select your test F75111 or F75113

2. select your test SMBus1(CO1) / SMBus2(CO2) "2i2o", "4i4o", "4i4o*2", "CIO116", "8I(CIO1)+8O(CIO2)", "1110"

3. start button , select single mode or looptest

F75111 Layout Picture



Introduction

Initial Internal F75111 port address (0x9c)

define GPIO1X, GPIO2X, GPIO3X to input or output and Enable WDT function pin

Set F75111 DI/DO (sample code as below Get Input value / Set output value)

DO: InterDigitalOutput(BYTE byteValue)
 DI: InterDigitalInput()

PULSE mode

Sample to setting GP33, 32, 31, 30 output 1mS low pulse signal.

```
{
this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_PULSE_CONTROL, 0x00);
//This is setting low pulse output
this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_PULSE_WIDTH_CONTROL, 0x01);
//This selects the pulse width to 1mS
this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_CONTROL_MODE, 0x0F);
//This is setting the GP33, 32, 31, 30 to output function.
this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_Output_Data , 0x0F);
//This is setting the GP33, 32, 31, 30 output data.
}
```

Initial internal F75111

```
void F75111::InitInternalF75111()
{
this->Write_Byte(F75111_INTERNAL_ADDR,GPIO1X_CONTROL_MODE,    0x00);
//set GPIO1X to Input function
this->Write_Byte(F75111_INTERNAL_ADDR,GPIO3X_CONTROL_MODE,    0x00);
//set GPIO3X to Input function
this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_CONTROL_MODE,    0xFF);
//set GPIO2X to Output function

this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_OUTPUT_DRIVING,  0xFF);
//set GPIO2X to Output Drving

this->Write_Byte(F75111_INTERNAL_ADDR,F75111_CONFIGURATION,  0x03);
//Enable WDT OUT function
}
```

Set output value

```
void F75111::InterDigitalOutput(BYTE byteValue)
{
BYTE byteData = 0;
byteData = (byteData & 0x01 )? byteValue + 0x01 : byteValue;
byteData = (byteData & 0x02 )? byteValue + 0x02 : byteValue;
byteData = (byteData & 0x04 )? byteValue + 0x04 : byteValue;
byteData = (byteData & 0x08 )? byteValue + 0x08 : byteValue;
byteData = (byteData & 0x10 )? byteValue + 0x10 : byteValue;
byteData = (byteData & 0x20 )? byteValue + 0x20 : byteValue;
byteData = (byteData & 0x40 )? byteValue + 0x40 : byteValue;
byteData = (byteData & 0x80 )? byteValue + 0x80 : byteValue;    // get value bit by bit

this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_OUTPUT_DATA,byteData);
// write byteData value via GPIO2X output pin
}
```

Get Input value

```
BYTE F75111::InterDigitalInput()
{
BYTE byteGPIO1X = 0;
BYTE byteGPIO3X = 0;
BYTE byteData = 0;

this->Read_Byte(F75111_INTERNAL_ADDR,GPIO1X_INPUT_DATA,&byteGPIO1X) ;
// Get value from GPIO1X
this->Read_Byte(F75111_INTERNAL_ADDR,GPIO3X_INPUT_DATA,&byteGPIO3X) ;
// Get value from GPIO3X

byteGPIO1X = byteGPIO1X & 0xF0; // Mask unuseful value
byteGPIO3X = byteGPIO3X & 0x0F; // Mask unuseful value

byteData = ( byteGPIO1X & 0x10 )? byteData + 0x01 : byteData;
byteData = ( byteGPIO1X & 0x80 )? byteData + 0x02 : byteData;
byteData = ( byteGPIO1X & 0x40 )? byteData + 0x04 : byteData;
byteData = ( byteGPIO3X & 0x01 )? byteData + 0x08 : byteData;

byteData = ( byteGPIO3X & 0x02 )? byteData + 0x10 : byteData;
byteData = ( byteGPIO3X & 0x04 )? byteData + 0x20 : byteData;
byteData = ( byteGPIO3X & 0x08 )? byteData + 0x40 : byteData;
byteData = ( byteGPIO1X & 0x20 )? byteData + 0x80 : byteData;
// Get correct DI value from GPIO1X & GPIO3X

return byteData;
}
```


define F75111 pin in F75111.h

```
//-----
#define F75111_INTERNAL_ADDR      0x9C // OnBoard F75111 Chipset
#define F75111_EXTERNAL_ADDR     0x6E // External F75111 Chipset
//-----
#define F75111_CONFIGURATION      0x03 // Configure GPIO13 to WDT2 Function
//-----
#define GPIO1X_CONTROL_MODE       0x10 // Select Output Mode or Input Mode
#define GPIO2X_CONTROL_MODE       0x20 // Select GPIO2X Output Mode or Input Mode
#define GPIO3X_CONTROL_MODE       0x40 // Select GPIO3X Output Mode or Input Mode
//-----
#define GPIO1X_INPUT_DATA         0x12 // GPIO1X Input Data Register
#define GPIO3X_INPUT_DATA         0x22 // GPIO2X Input Data Register
#define GPIO3X_INPUT_DATA         0x42 // GPIO3X Input Data Register
//-----
#define GPIO1X_OUTPUT_DATA        0x11 // GPIO1X Output Data Register
#define GPIO2X_OUTPUT_DATA        0x21 // GPIO2X Output Data Register
#define GPIO3X_OUTPUT_DATA        0x41 // GPIO3X Output Data Register
//-----
#define GPIO1X_OUTPUT_DRIVING     0x1B // Select GPIO1X Output Driving Enable
#define GPIO2X_OUTPUT_DRIVING     0x2B // Select GPIO2X Output Driving Enable
#define GPIO3X_OUTPUT_DRIVING     0x4B // Select GPIO3X Output Driving Enable
//-----
#define GPIO1X_PULSE_CONTROL      0x13 // GPIO1x Level/Pulse Control Register
// 0:Level Mode
// 1:Pulse Mode
#define GPIO1X_PULSE_WIDTH_CONTROL 0x14 // GPIO1x Pulse Width Control Register
#define GP1_PSWIDTH_500US         0x00 // When select Pulse mode:500 us.
#define GP1_PSWIDTH_1MS           0x01 // When select Pulse mode:1 ms.
#define GP1_PSWIDTH_20MS          0x02 // When select Pulse mode:20 ms.
#define GP1_PSWIDTH_100MS         0x03 // When select Pulse mode:100 ms.
//-----
#define GPIO2X_PULSE_CONTROL      0x23 // GPIO2x Level/Pulse Control Register
// 0:Level Mode
// 1:Pulse Mode
#define GPIO2X_PULSE_WIDTH_CONTROL 0x24 // GPIO2x Pulse Width Control Register
#define GP2_PSWIDTH_500US         0x00 // When select Pulse mode:500 us.
#define GP2_PSWIDTH_1MS           0x01 // When select Pulse mode:1 ms.
#define GP2_PSWIDTH_20MS          0x02 // When select Pulse mode:20 ms.
#define GP2_PSWIDTH_100MS         0x03 // When select Pulse mode:100 ms.
//-----
#define GPIO3X_PULSE_CONTROL      0x43 // GPIO3x Level/Pulse Control Register
// 0:Level Mode
// 1:Pulse Mode
#define GPIO3X_Output_Data        0x41 // GPIO3x Output Data Register
#define GPIO3X_PULSE_WIDTH_CONTROL 0x44 // GPIO3x Pulse Width Control Register
#define GP3_PSWIDTH_500US         0x00 // When select Pulse mode:500 us.
#define GP3_PSWIDTH_1MS           0x01 // When select Pulse mode:1 ms.
#define GP3_PSWIDTH_20MS          0x02 // When select Pulse mode:20 ms.
#define GP3_PSWIDTH_100MS         0x03 // When select Pulse mode:100 ms.
//-----
```

3-8-3 IO Device: F75111 CIO Utility Console under linux

http://tprd.info/lexwiki/index.php/IO_Device:F75111_CIO_Utility_Console_under_linux

The Sample code source you can download from

<Google Drive>

Source file: CIO_Utility_Console_v1.4L_Src

Binary file: CIO_Utility_Console_v1.4L_Bin

<FTP>

Source file: CIO_Utility_Console_v1.4L_Src

Binary file: CIO_Utility_Console_v1.4L_Bin

MB Support List

Ivybridge	BayTrail	Apollo Lake	Skylake/Kabylake	Card
2I847H	1I385A/H	2I390CW	2I610DW/HW	CIO116-G
3I8347A/CW	1I386HW	2I390CW	2I610HW	E691A
3I847NX/NM	2I380A/NX	3I390AW	3I610DW	
3I847D(OEM)	2I382A	3I390D(OEM)	PM610DW	
3I847HW	2I385A/BW/CW/ EW/HW/PW	3I390NX	ST610W	
CI847A/C	3I380A/CW/D/NX	3I393NX	3I170DW/HW/NX	
3I770A/CW	3I385AW/CW	PM390CW	CI170A/C	
CI770A/C	ST385W		PM170DW	

How to use this Demo Application

```
root@test-2I386AW: /home/test/Desktop
File Edit View Search Terminal Help
root@test-2I386AW:/home/test/Desktop# ./CIO_Utility_console
Usage: ./CIO_Utility_console [OPTION] ... [--mode value]

-h           ,--help           printf this help and exit
-s DOx , --setDo value | value:number of bits
-r DIx , --readD value | value:number of bits
-L vale,--LEDSET value | sample: --LEDSET 0x00 ,LED 0-7 all on
                    | sample: --LEDSET 0xff ,LED 0-7 all off
                    | sample: --LEDSEr 0x0f ,LED 4-7 all on , LED 0-3 all off
                    | sample: --LEDSEr 0xf0 ,LED 4-7 all off , LED 0-3 all on
--mode value | mode1:2i2o mode2:4i4o mode3:8i8o value:loop number
Example:
./CIO_Utility --2i2o 4
```

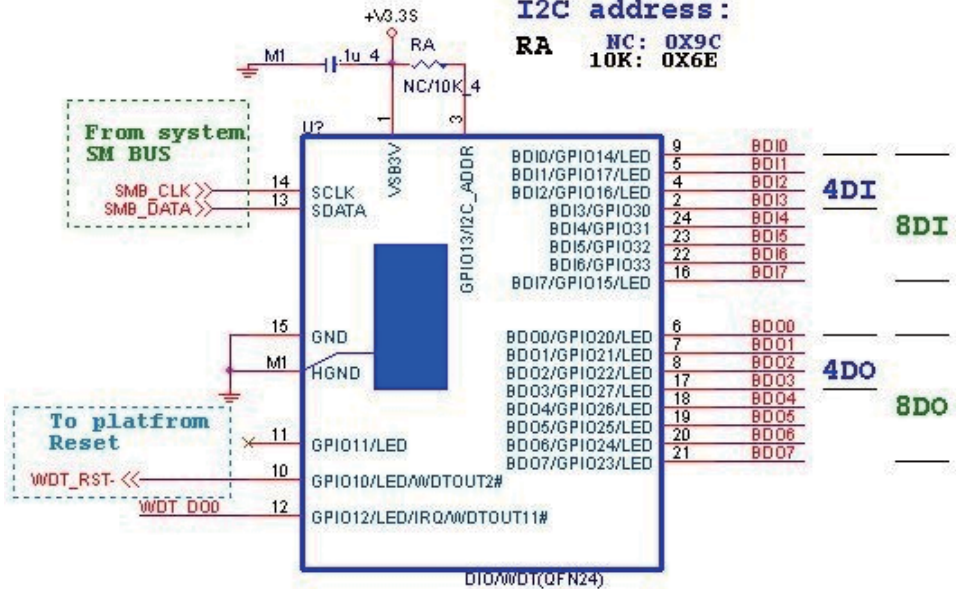
1. The program must control I/O device, when you use this you must change user to root, you can use this command "sudo su"

2. enter "./CIO_Utility_console -h"show help function

Example:

CIO_Utility_console --4i4o 1

F75111 Layout Picture



Introduction

Initial Internal F75111 port address (0x9c)

define GPIO1X, GPIO2X, GPIO3X to input or output
 and Enable WDT function pin

Set F75111 DI/DO (sample code as below Get Input value / Set output value)

DO: InterDigitalOutput (BYTE byteValue)
 DI: InterDigitalInput()

PULSE mode

Sample to setting GP33, 32, 31, 30 output 1mS low pulse signal.

```
{
  this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_PULSE_CONTROL      0x00);
  //This is setting low pulse output
  this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_PULSE_WIDTH_CONTROL, 0x01);
  //This selects the pulse width to 1mS
  this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_CONTROL_MODE,     0x0F);
  //This is setting the GP33, 32, 31, 30 to output function.
  this->Write_Byte(F75111_INTERNAL_ADDR, GPIO3X_Output_Data ,     0x0F);
  //This is setting the GP33, 32, 31, 30 output data.
}
```

Initial internal F75111

```
void F75111::InitInternalF75111()
{
    this->Write_Byte(F75111_INTERNAL_ADDR,GPIO1X_CONTROL_MODE,    0x00); //set GPIO1X to Input function;
    this->Write_Byte(F75111_INTERNAL_ADDR,GPIO3X_CONTROL_MODE,    0x00); //set GPIO3X to Input function;
    this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_CONTROL_MODE,    0xFF); //set GPIO2X to Output function;
    this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_OUTPUT_DRIVING,  0xFF); //set GPIO2X to Output Driving;
    this->Write_Byte(F75111_INTERNAL_ADDR,F75111_CONFIGURATION,  0x03); //Enable WDT OUT function;
}
```

Set output value

```
void F75111::InterDigitalOutput(BYTE byteValue)
{
    BYTE byteData = 0;
    byteData = (byteData & 0x01 )? byteValue + 0x01 : byteValue;
    byteData = (byteData & 0x02 )? byteValue + 0x02 : byteValue;
    byteData = (byteData & 0x04 )? byteValue + 0x04 : byteValue;
    byteData = (byteData & 0x08 )? byteValue + 0x08 : byteValue;
    byteData = (byteData & 0x10 )? byteValue + 0x10 : byteValue;
    byteData = (byteData & 0x20 )? byteValue + 0x20 : byteValue;
    byteData = (byteData & 0x40 )? byteValue + 0x40 : byteValue;
    byteData = (byteData & 0x80 )? byteValue + 0x80 : byteValue;    // get value bit by bit

    this->Write_Byte(F75111_INTERNAL_ADDR,GPIO2X_OUTPUT_DATA,byteData);
    // write byteData value via GPIO2X output pin
}
```

Get Input value

```
BYTE F75111::InterDigitalInput()
{
    BYTE byteGPIO1X = 0;
    BYTE byteGPIO3X = 0;
    BYTE byteData = 0;
    this->Read_Byte(F75111_INTERNAL_ADDR,GPIO1X_INPUT_DATA,&byteGPIO1X); // Get value from GPIO1X;
    this->Read_Byte(F75111_INTERNAL_ADDR,GPIO3X_INPUT_DATA,&byteGPIO3X); // Get value from GPIO3X

    byteGPIO1X = byteGPIO1X & 0xF0; // Mask unuseful value
    byteGPIO3X = byteGPIO3X & 0x0F; // Mask unuseful value

    byteData = ( byteGPIO1X & 0x10 )? byteData + 0x01 : byteData;
    byteData = ( byteGPIO1X & 0x08 )? byteData + 0x02 : byteData;
    byteData = ( byteGPIO1X & 0x04 )? byteData + 0x04 : byteData;
    byteData = ( byteGPIO3X & 0x01 )? byteData + 0x08 : byteData;

    byteData = ( byteGPIO3X & 0x02 )? byteData + 0x10 : byteData;
    byteData = ( byteGPIO3X & 0x04 )? byteData + 0x20 : byteData;
    byteData = ( byteGPIO3X & 0x08 )? byteData + 0x40 : byteData;
    byteData = ( byteGPIO1X & 0x20 )? byteData + 0x80 : byteData; // Get correct DI value from GPIO1X & GPIO3X;

    return byteData;
}
```

define F75111 pin in F75111.h

```
//-----  
#define F75111_INTERNAL_ADDR      0x9C // OnBoard F75111 Chipset  
#define F75111_EXTERNAL_ADDR     0x6E // External F75111 Chipset  
//-----  
#define F75111_CONFIGURATION     0x03 // Configure GPIO13 to WDT2 Function  
//-----  
#define GPIO1X_CONTROL_MODE      0x10 // Select Output Mode or Input Mode  
#define GPIO2X_CONTROL_MODE      0x20 // Select GPIO2X Output Mode or Input Mode  
#define GPIO3X_CONTROL_MODE      0x40 // Select GPIO3X Output Mode or Input Mode  
//-----  
#define GPIO1X_INPUT_DATA        0x12 // GPIO1X Input Data Register  
#define GPIO2X_INPUT_DATA        0x22 // GPIO2X Input Data Register  
#define GPIO3X_INPUT_DATA        0x42 // GPIO3X Input Data Register  
//-----  
#define GPIO1X_OUTPUT_DATA       0x11 // GPIO1X Output Data Register  
#define GPIO2X_OUTPUT_DATA       0x21 // GPIO2X Output Data Register  
#define GPIO3X_OUTPUT_DATA       0x41 // GPIO3X Output Data Register  
//-----  
#define GPIO1X_OUTPUT_DRIVING    0x1B // Select GPIO1X Output Driving Enable  
#define GPIO2X_OUTPUT_DRIVING    0x2B // Select GPIO2X Output Driving Enable  
#define GPIO3X_OUTPUT_DRIVING    0x4B // Select GPIO3X Output Driving Enable  
//-----  
#define GPIO1X_PULSE_CONTROL     0x13 // GPIO1x Level/Pulse Control Register  
// 0:Level Mode  
// 1:Pulse Mode  
#define GPIO1X_PULSE_WIDTH_CONTROL 0x14 // GPIO1x Pulse Width Control Register  
#define GP1_PSWIDTH_500US        0x00 // When select Pulse mode: 500us.  
#define GP1_PSWIDTH_1MS          0x01 // When select Pulse mode: 1ms.  
#define GP1_PSWIDTH_20MS         0x02 // When select Pulse mode: 20ms.  
#define GP1_PSWIDTH_100MS        0x03 // When select Pulse mode: 100ms.  
//-----  
#define GPIO2X_PULSE_CONTROL     0x23 // GPIO2x Level/Pulse Control Register  
// 0:Level Mode  
// 1:Pulse Mode  
#define GPIO2X_PULSE_WIDTH_CONTROL 0x24 // GPIO2x Pulse Width Control Register  
#define GP2_PSWIDTH_500US        0x00 // When select Pulse mode: 500us.  
#define GP2_PSWIDTH_1MS          0x01 // When select Pulse mode: 1ms.  
#define GP2_PSWIDTH_20MS         0x02 // When select Pulse mode: 20ms.  
#define GP2_PSWIDTH_100MS        0x03 // When select Pulse mode: 100ms.  
//-----  
#define GPIO3X_PULSE_CONTROL     0x43 // GPIO3x Level/Pulse Control Register  
// 0:Level Mode  
// 1:Pulse Mode  
#define GPIO3X_Output_Data       0x41 // GPIO3x Output Data Register  
#define GPIO3X_PULSE_WIDTH_CONTROL 0x44 // GPIO3x Pulse Width Control Register  
#define GP3_PSWIDTH_500US        0x00 // When select Pulse mode: 500 us.  
#define GP3_PSWIDTH_1MS          0x01 // When select Pulse mode: 1 ms.  
#define GP3_PSWIDTH_20MS         0x02 // When select Pulse mode: 20 ms.  
#define GP3_PSWIDTH_100MS        0x03 // When select Pulse mode: 100 ms.  
//-----
```

3-9 LAN Interface

● **CL1 / CL2: RJ45 LAN port Giga / 100Mb(RJ45 Jack)**

PIN NO.	Description	PIN NO.	Description
1	TR0-/TX+	5	TR2-/NC
2	TR0+/TX-	6	TR2+/RX-
3	TR1-/RX+	7	TR3-/NC
4	TR1+/NC	8	TR3+/NC

● **CL11 / CL21: LAN port Giga / 100Mb 2x5pin (2.0mm) wafer**

PIN NO.	Description	PIN NO.	Description
1	TR0-/TX+	2	TR0+/TX-
3	TR2+/NC	4	TR1+/RX-
5	TR1-/RX+	6	TR2-/NC
7	TR3-/NC	8	TR3+/NC

● **RJ45 LAN Connector--- LED define Giga / 100 / 10MB Connector**

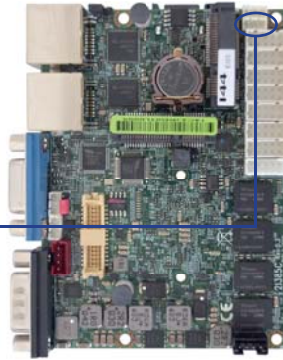
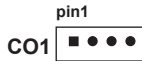
SPEED		10 Mbps			100Mbps			1000 Mbps		
Indicate	Side	Back		Front	Back		Front	Back		Front
	LED	Link	ACT	ACT	Link	ACT	ACT	Link	ACT	ACT
LAN Light			Orange	Orange	Green	Orange	Orange	Red	Orange	Orange



3-10 SMBus Interface

- CO1: SMBus 4pin (1.25mm)Wafer

PIN NO.	Description
1	+3.3V
2	GND
3	SMBus Clock
4	SMBus DATA

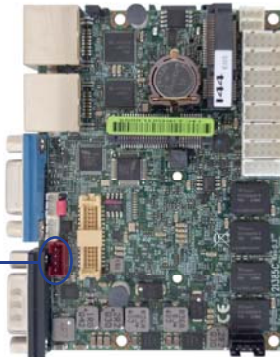
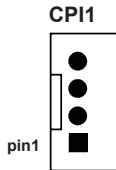


3-11 DC Power Input

- CPI1: DC-in 1x4 (2.0mm) Wafer Internal connector (Red)

PIN NO.	Description
2,3	DC-IN (12V)
1,4	GND

Note: Very important check Dc-in Voltage

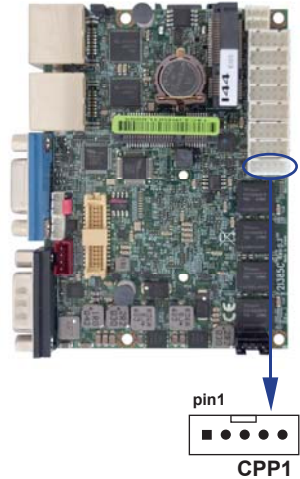


3-12 Panel Inverter power

● **CPP1: Panel Inverter power (5pin 2.0mm wafer)**

PIN NO.	Description
1	+12V
2	GND
3	PWM dimming
4	ENBKL (3.3V)
5	ENBKL (5V)

- Note: 1. JVP1 Inverter Voltage select
 2. CPP1 PIN 3 and LVDS1 PIN1 is same signal.
 3. Pin 3 back light dimming control,
 Provided 200Hz / 275Hz / 380Hz / 20KHz / 25KHz
 and adjust PWM duty cycle by software program.

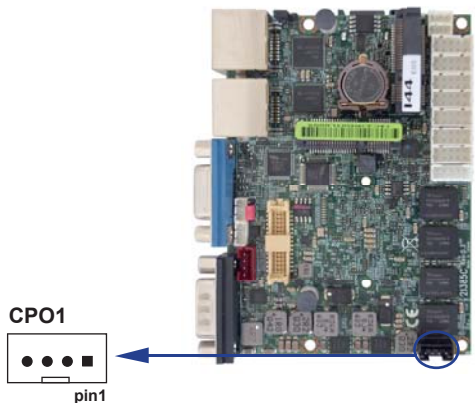


3-13 DC+12V / +5 Voltage Power output (4pin 2.0mm Wafer)(Black)

● **CPO1: +12V/+5V DC voltage output**

PIN NO.	Description
1	+5V
2	GND
3	GND
4	+12V*

* Note: Attention! Check Device Power in spec



3-14 Touch screen device

- CT1: Touch screen (2x5 pin 2.0mm wafer) USB interface.

- For 8-wire type pin define

PIN NO.	Description	PIN NO.	Description
1	Bottom	2	Bottom Sense
3	Top Sense	4	Top
5	Right	6	Right Sense
7	Left	8	Left Sense
9	GND	10	NC

Note: For eight wire type cable Pin 3 and Pin4 need short.

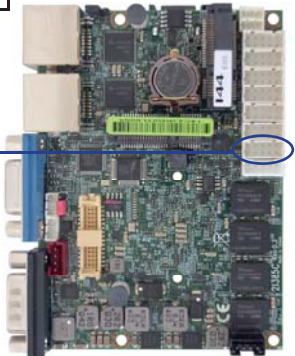
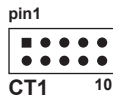
- For 4-wire type pin define

PIN NO.	Description	PIN NO.	Description
1	Bottom	2	N/A
3	N/A	4	Top
5	Right	6	N/A
7	Left	8	N/A
9	GND	10	KEY

Note: For four wire type cable Pin 3 and Pin4 need short.

- For 5-wire type pin define

PIN NO.	Description	PIN NO.	Description
1	UR(H)	2	N/A
3	Sense	4	UL(Y)
5	LR(X)	6	N/A
7	LL(L)	8	N/A
9	GND	10	KEY



3-15 USB Interface

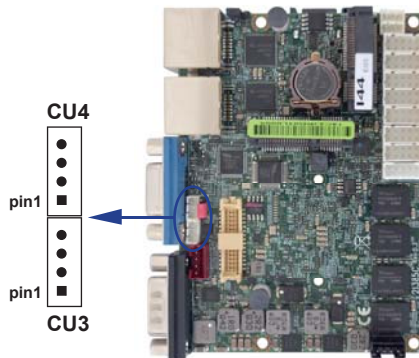
● **CU1/CU2: USB 2.0 Port Type A**

PIN NO.	Description
1	+5V
2	DATA -
3	DATA +
4	GND



● **CU3 / CU4: USB 2.0 Port (1x4pin 1.25mm Wafer)**

PIN NO.	Description
1	+5V
2	DATA -
3	DATA +
4	GND

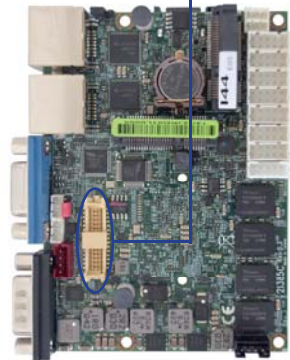
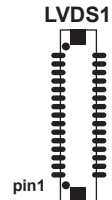


3-16 LVDS Connector

• LVDS1: LVDS interface (2x15pin 1.25mm wafer)

PIN NO.	Description	PIN NO.	Description
1	PWM dimming	2	+5V
3	+LCD(5V or 3.3V)	4	+LCD(5V or 3.3V)
5	Channel-1-DATA3+	6	Channel-0-DATA3+
7	Channel-1-DATA3-	8	Channel-0-DATA3-
9	Channel-0-DATA2+	10	Channel-0-CLK+
11	Channel-0-DATA2-	12	Channel-0-CLK-
13	GND	14	GND
15	Channel-0-DATA1+	16	Channel-0-DATA0+
17	Channel-0-DATA1-	18	Channel-0-DATA0-
19	GND	20	GND
21	+LCD(5V or 3.3V)	22	+LCD(5V or 3.3V)
23	Channel-1-DATA2+	24	Channel-1-CLK+
25	Channel-1-DATA2-	26	Channel-1-CLK-
27	Channel-1-DATA1+	28	Channel-1-DATA0+
29	Channel-1-DATA1-	30	Channel-1-DATA0-

- Note:
1. LVDS interface support 18 / 24bits two channel.
 2. JVL1: LVDS panel +5V / +3.3V (default) Voltage select.
 3. LVDS1 PIN 1 for panel backlight active.
 4. Pin 1 back light dimming control.
Provided 200Hz / 275Hz / 380 Hz / 20KHz / 25KHz
and adjust PWM duty cycle by software program.



3-17 SATA Interface

● SATA1: SATA Port 1x7pin connector

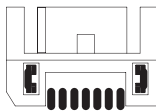
PIN NO.	Description
1	GND
2	TX+
3	TX-
4	GND
5	RX-
6	RX+
7	GND

Note: 1. SATA1 support SATA 2.0 spec update 3Gb/sec.

2. CPO1 provide SATA HDD power +12V, GND, +5V

3. The SATA signal share with mSATA of MPCE1, but just one can be worked in same time.

SATA1



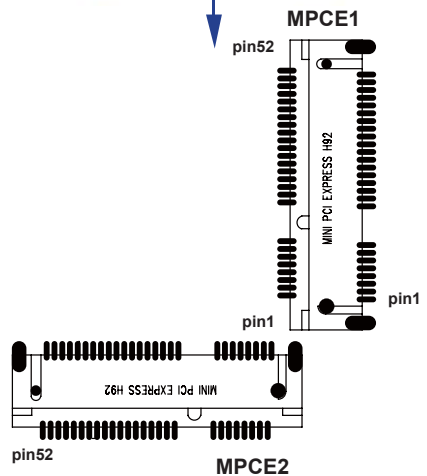
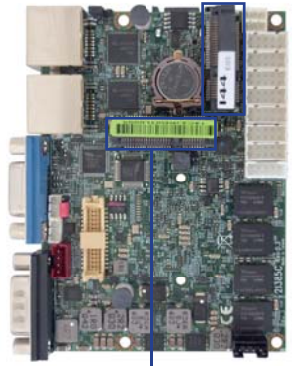
3-18 PCI Express Mini card

●MPCE1 / MPCE2: Support USB and PCIe by one Interface (Mini card socket 52pin)

MPCE1: Full size mini card

MPCE2: Half size mini card

PIN NO.	Description	PIN NO.	Description
1	NC	2	+3.3V
3	NC	4	GND
5	NC	6	+1.5V
7	NC	8	NC
9	GND	10	NC
11	PCIe-CLK-	12	NC
13	PCIe-CLK+	14	NC
15	GND	16	NC
KEY			
17	NC	18	GND
19	NC	20	NC
21	GND	22	Reset
23	PCIe-RX-/mSATA-RX+	24	+3.3V
25	PCIe-RX+/mSATA-RX-	26	GND
27	GND	28	+1.5V
29	GND	30	SMB-CLK
31	PCIe-TX-/mSATA-TX-	32	SMB-DATA
33	PCIe-TX+/mSATA-TX+	34	GND
35	GND	36	USB-DATA-
37	GND	38	USB-DATA+
39	+3.3V	40	GND
41	+3.3V	42	NC
43	GND	44	NC
45	NC	46	NC
47	NC	48	+1.5V
49	NC	50	GND
51	mSATA/PCIe detect	52	+3.3V



Note: MPCE1 Pin51 mSATA / PCIe auto detect function

The mSATA signal share with SATA of SATA1, but just one can be worked in same time.

3-19 Connector wafer of Compatible Brand and part number list

Location	CKTS	PITCH	Brand Name	Mating connector	Cable housing
CA3	2x5 10Pin	2.0mm	JST	B10B-PHDSS	PHDR-10VS
CALR1	1x4 4Pin	1.25mm	MOLEX	53047-0410	51021-0400
CC2	2x5 10Pin	2.0mm	JST	B10B-PHDSS	PHDR-10VS
CC3	2x5 10Pin	2.0mm	JST	B10B-PHDSS	PHDR-10VS
CC4	2x5 10Pin	2.0mm	JST	B10B-PHDSS	PHDR-10VS
CFP1	2x5 10Pin	2.0mm	JST	B10B-PHDSS	PHDR-10VS
CIO1	2x5 10Pin	2.0mm	JST	B10B-PHDSS	PHDR-10VS
CL11	2x4 8Pin	2.0mm	JST	B8B-PHDSS	PHDR-08VS
CL21	2x4 8Pin	2.0mm	JST	B8B-PHDSS	PHDR-08VS
CO1	1x4 4Pin	1.25mm	MOLEX	53047-0410	51021-0400
CPI1	1x4 4Pin	2.0mm	JST	B4B-PH-KL	PHR-4
CPP1	1x5 5Pin	2.0mm	JST	B5B-PH-KL	PHR-5
CPO1	1x4 4Pin	2.0mm	JST	B4B-PH-KL	PHR-4
CT1	2x5 10Pin	2.0mm	GND	B10B-PHDSS	PHDR-10VS
CU3	1x4 4Pin	1.25mm	MOLEX	53047-0410	51021-0400
CU4	1x4 4Pin	1.25mm	MOLEX	53047-0410	51021-0400
LVDS1	2x15 30Pin	1.25mm	HIROSE	DF13-30DS-1.25C	DF13-30DP-1.25V

Chapter-4

Introduction of BIOS

The BIOS is a program located in the Flash Memory on the motherboard.

This program is a bridge between motherboard and operating system.

When you start the computer, the BIOS program gains control.

The BIOS first operates an auto-diagnostic test called POST (Power on Self Test) for all the necessary hardware, it detects the entire hardware devices and configures the parameters of the hardware synchronization. After these tasks are completed, BIOS will give control of the computer back to operating system (OS).

Since the BIOS is the only channel for hardware and software to communicate with, it is the key factor of system stability and of ensuring your system performance at best.

In the BIOS Setup main menu, you can see several options. We will explain these options in the following pages. First, let us see the function keys you may use here:

Press <Esc> to quit the BIOS Setup.

Press ↑↓←→(up, down, left, right) to choose the option you want to confirm or modify.

Press <F10> to save these parameters and to exit the BIOS Setup menu after you complete the setup of BIOS parameters.

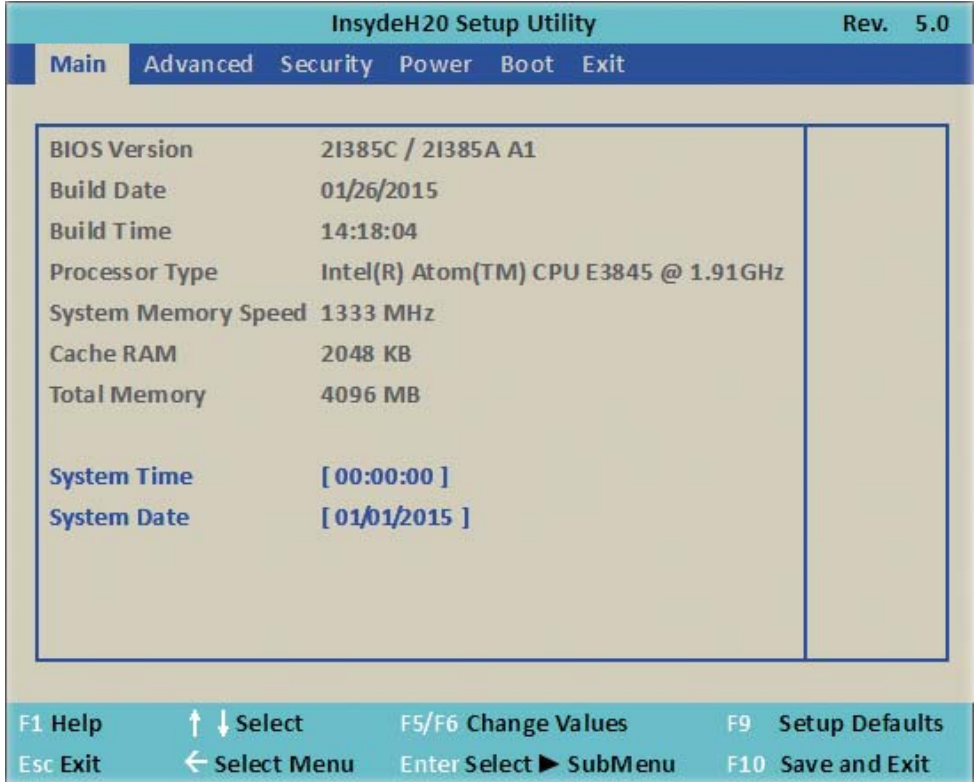
Press Page Up/Page Down or +/- keys to modify the BIOS parameters for the active option.

4-1 Enter Setup

Power on the computer and press key immediately to enter Setup.

If the message disappears before your respond but you still wish to enter Setup, restart the system by turning it OFF then ON. You may also restart the system by simultaneously pressing <Ctrl>, <Alt> and <Delete> keys.

4-2 BIOS Menu Screen & Function Keys



In the above BIOS Setup main menu of, you can see several options.

We will explain these options step by step in the following pages of this chapter, but let us first see a short description of the function keys you may use here:

- Press ←→ (left, right) to select screen;
- Press ↑↓ (up, down) to choose, in the main menu, the option you want to confirm or to modify.
- Press <Enter> to select.
- Press <+>/<-> keys when you want to modify the BIOS parameters for the active option.
- [F1]: General help.
- [F2]: Previous value.
- [F3]: Optimized defaults.
- [F4]: Save & Reset.
- Press <Esc> to quit the BIOS Setup.

4-3 Getting Help

The screenshot shows the InsydeH20 Setup Utility interface. At the top, there is a title bar with "InsydeH20 Setup Utility" on the left and "Rev. 5.0" on the right. Below the title bar is a navigation menu with options: "Main", "Advanced", "Security", "Power", "Boot", and "Exit". The main content area is titled "[General Help]" and contains the following text:

The Setup Utility is a ROM-based configuration utility that displays the system's configuration status and provides users with a tool to set their system parameters. Setting incorrect values may cause system boot failure:

Load setup default values to recover

- <Left/Right> Select Screen
- <Up/Down> Select Item
- <Enter> Select or Enter SubMenu
- <F9> Load Setup Default
- <F10> Save and Exit
- <ESC> Exit Setup
- <F1> key displays General Help(This Screen)

At the bottom of the help window, there are three lines of instructions:

- Push Enter/ESC -- Leave
- Push PageUp -- previous
- Push PageDown -- Next Page

Below the help window, there is a legend for navigation keys:

F1 Help	↑ ↓ Select	F5/F6 Change Values	F9 Setup Defaults
Esc Exit	← Select Menu	Enter Select ► SubMenu	F10 Save and Exit

Status Page Setup Menu/ Option Page Setup Menu

Press F1 to pop up a help window that describes the appropriate keys to use and the possible selections for the highlighted item. To exit the Help Window, press <Esc>.

4-4 Menu Bars

There are six menu bars on top of BIOS screen:

Main To change system basic configuration

Advanced To change system advanced configuration

Security Password settings

Power PME & Power button settings

Boot Exit Save setting, loading and exit options.

User can press the right or left arrow key on the keyboard to switch from menu bar.

The selected one is highlighted.

4-5 Main

InsydeH20 Setup Utility		Rev. 5.0
Main Advanced Security Power Boot Exit		
BIOS Version	2I385C / 2I385A A1	
Build Date	01/19/2015	
Build Time	14:18:04	
Processor Type	Intel(R) Atom(TM) CPU E3845 @ 1.91GHz	
System Memory Speed	1333 MHz	
Cache RAM	2048 KB	
Total Memory	4096 MB	
System Time	[00:00:00]	
System Date	[01/01/2015]	
F1 Help	↑ ↓ Select	F5/F6 Change Values
Esc Exit	← Select Menu	Enter Select ► SubMenu
		F9 Setup Defaults
		F10 Save and Exit

Main menu screen includes some basic system information. Highlight the item and then use the <+> or <-> and numerical keyboard keys to select the value you want in each item.

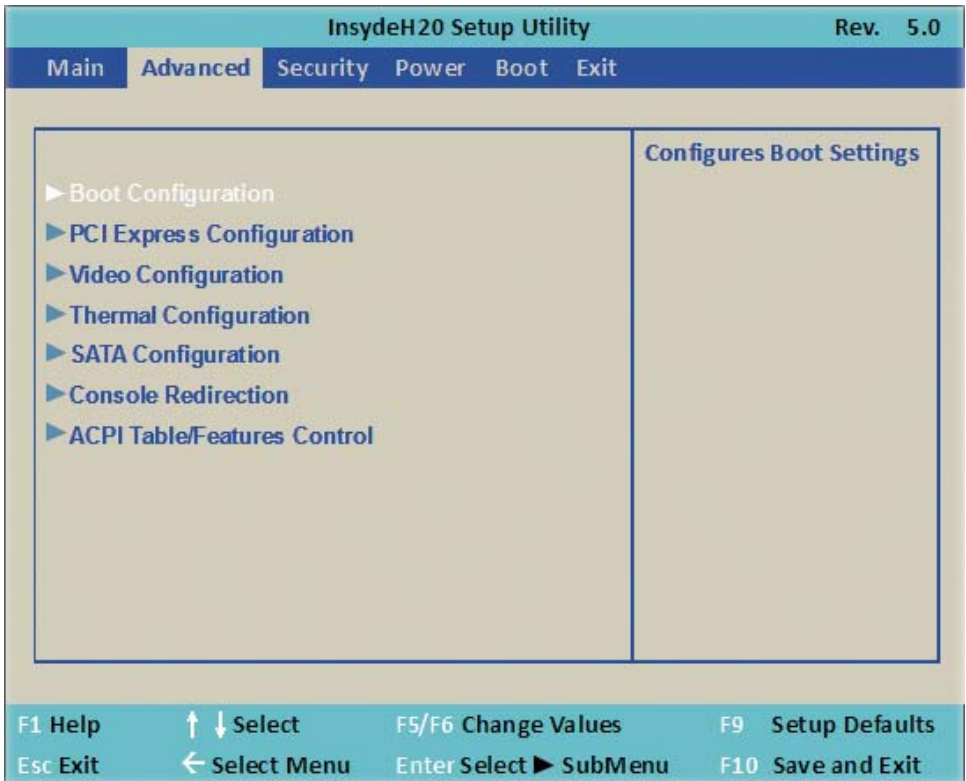
System Date

Set the Date. Please use [Tab] to switch between data elements.

System Time

Set the Time. Please use [Tab] to switch between data elements.

4-6 Advanced



Boot Configuration

Please refer section 4-6-1

PCI Express Configuration

Please refer section 4-6-2

Video Configuration

Please refer section 4-6-3

Thermal Configuration

Please refer section 4-6-4

SATA Configuration

Please refer section 4-6-5

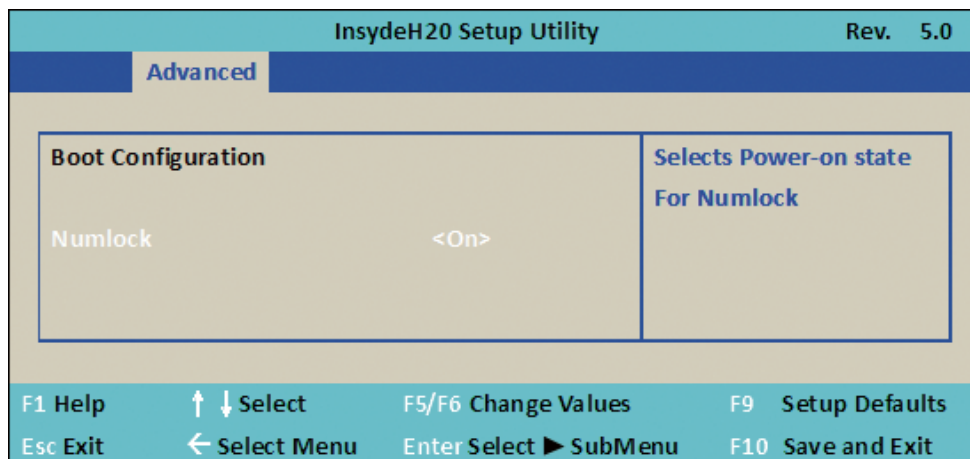
Console Redirection

Please refer section 4-6-6

ACPI Table/Features Control

Please refer section 4-6-7

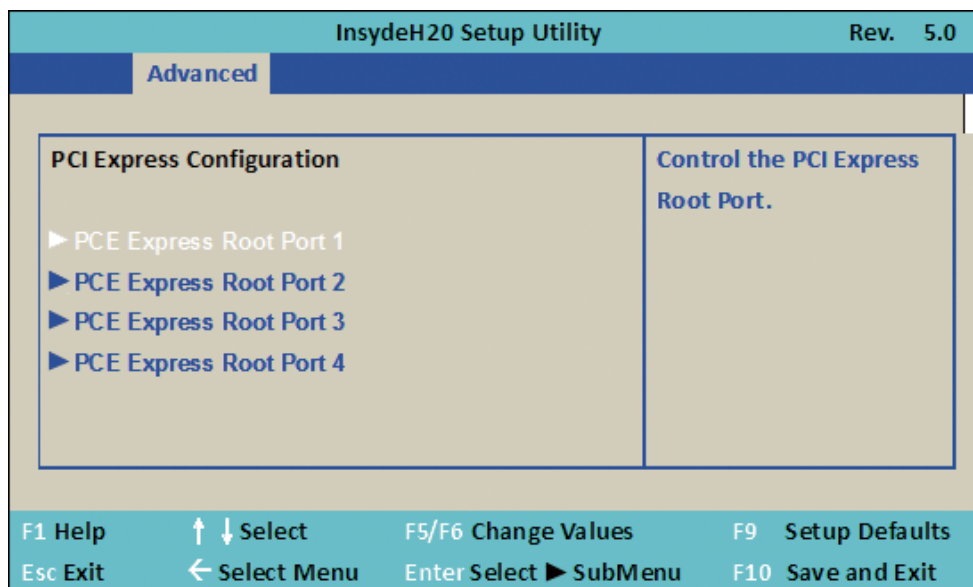
4-6-1 Boot Configuration



Numlock

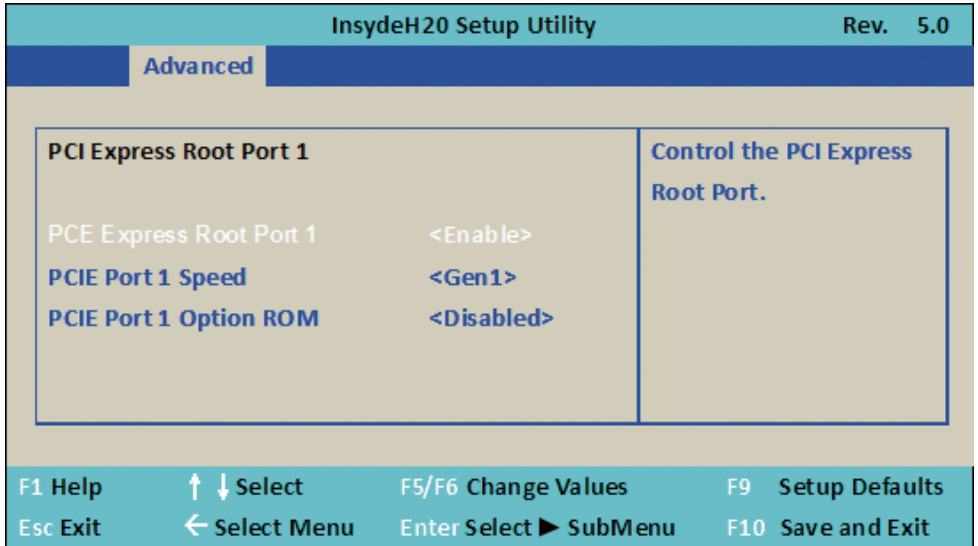
Select Power-on state for Numlock, default is <ON>

4-6-2 PCI Express Configuration



PCIe 1/2/3/4 configuration settings

4-6-2-1 ► PCI Express Root Port 1/2/3/4



Control the PCI Express Root Port.

The optional settings are: Enabled(default), Disabled.

Select PCI Express port speed.

The optional settings are: Gen1(default), Gen2

Select PCIE TXE ROM support

The optional settings are: Disabled(default), Enabled

4-6-3 Video Configuration

InsydeH20 Setup Utility		Rev. 5.0
Advanced		
Vedio Configuration		Select Hardware CRT Configuration.
Configure CRT as	<CRT>	
Configure DD11 as	<LVDS>	
Configure LVDS Panel Number as	<1024 x 768 18bit>	
Aperture Size	<256MB>	
IGD – DVMT Pre-Allocated	<64M>	
IGD – DVMT Total Gfx Mem	<256M>	
F1 Help	↑ ↓ Select	F5/F6 Change Values
Esc Exit	← Select Menu	Enter Select ► SubMenu
		F9 Setup Defaults
		F10 Save and Exit

Configure LVDS Panel Number as

The Panel resolution supported are below:

- 640 x 480 18bit
- 800 x 600 18bit
- 1024 x 768 18bit (default)
- 800 x 480 18bit
- 1024 x 600 18bit
- 1280 x 800 18bit
- 1366 x 768 18bit
- 800 x 600 24bit
- 1024 x 768 24bit
- 1280 x 800 24bit
- 1366 x 768 24bit
- 1280 x 1024 48bit
- 1440 x 900 48bit
- 1600 x 1200 48bit
- 1920 x 1080 48bit

Aperture Size

The optional settings are: 128MB, 256MB(default), 512MB.

IGD - DVMT Pre-Allocated

Use this item to select DVMT 5.0 pre-allocated (fixed) graphics memory size used by the internal graphics device.

The optional settings are: 64(default)/96/128/160/192/224/256/288/320/352/384/416/448/480/512MB

IGD - DVMT Total Gfx Mem

Use this item to select DVMT 5.0 total graphics memory size used by the internal graphics device

The optional settings are:128M, 256M(default), MAX

4-6-4 Thermal Configuration

InsydeH20 Setup Utility Rev. 5.0

Advanced

Thermal Configuration Parameters		This value controls the temperature of The ACPI Critical Trip Point – the point in Which the OS will Shut the system off.
Critical Trip Point	<110 °C>	
Passive Trip Point	<105 °C>	

NOTE: 100C is the Plan of Record (POR) For all Intel mobile processors.

F1 Help ↑ ↓ Select F5/F6 Change Values F9 Setup Defaults
Esc Exit ← Select Menu Enter Select ► SubMenu F10 Save and Exit

Thermal Configuration Parameters

This Value controls the temperature of the ACPI Critical Trip Point, the point in which the OS will shutdown the system.

Critical Trip point is the shutdown temperature, the default value is 110°

The CPU frequency will auto reduce when cpu temperature arrived to passive Trip point.

The default of the passive trip point is 105°

4-6-5 SATA Configuration

InsydeH20 Setup Utility		Rev. 5.0
Advanced		
SATA Configuration		DISABLED: Disables SATA Controller.
SATA Controller	<Enabled>	
Chipset SATA Mode	<IDE>	ENABLED: Enables SATA Controller.
SATA Speed	<Gen1>	
IDE Mode	<Native IDE>	
SATA Port 0 Connected to an ODD	<Enabled>	
SATA Port 1 Connected to an ODD	<Enabled>	
? Serial ATA Port 0	[Not Installed]	
? Serial ATA Port 1	[Not Installed]	
F1 Help	↑ ↓ Select	F5/F6 Change Values
Esc Exit	← Select Menu	F9 Setup Defaults
		F10 Save and Exit
		Enter Select ► SubMenu

SATA Controller

Use this item to Enable or Disable SATA Device.

The optional settings are: Enabled(default) or Disabled

Chipset SATA Mode

Determine how SATA controller(s) operate.

The optional settings are: IDE Mode(default), AHCI Mode.

SATA Speed

Indicates the maximum speed the SATA controller can support.

The optional settings: Gen1, Gen2(default).

IDE Mode

Legacy IDE or Native IDE MODE,

The optional settings: Legacy IDE or Native IDE(default)

SATA Port 0 Connected to an ODD

Use this item to Enable or Disable SATA Port0 ODD function

The optional settings are: Enabled(default) or Disable

SATA Port 1 Connected to an ODD

Use this item to Enable or Disable SATA Port1 ODD function

The optional settings are: Enabled(default) or Disable

4-6-6 Console Redirection

InsydeH2O Setup Utility		Rev. 5.0
Advanced		
Console Redirection Setup		
Console Serial Redirect	<Enabled>	
Text Mode Resolution	<Force 80x24 (DEL LAST ROW)>	
Terminal Type	<VT_100>	
Baud Rate	<115200>	
Data Bits	<8 Bits>	
Parity	<None>	
Stop Bits	<1 Bits>	
Flow control	<None>	
F1 Help	↑ ↓ Select	F5/F6 Change Values
Esc Exit	← Select Menu	Enter Select ► SubMenu
		F9 Setup Defaults
		F10 Save and Exit

Console Serial Redirect

Use this item to enable or disable Console Redirection.

The optional settings are: Enabled, Disabled(default).

Text Mode Resolution

The optional settings are: Force 80x25

Force 80x24(DEL FIRST ROW)

Force 80x24(DEL LAST ROW)

Baud Rate

The optional settings are: 115200(default) , 57600 , 38400 , 19200 , 9600 , 4800 , 2400 , 1200

Data Bits

The optional settings are: 8 Bits(default) , 7 Bits

Parity

The optional settings are: None(default) , Even , Odd

Stop Bits

The optional settings are: 1 Bit(default) , 2 Bits

Flow Control

The optional settings are: None(default) , RTS/CTS , XON/XOFF

4-6-7 ACPI Table/Features Control

InsydeH20 Setup Utility		Rev. 5.0
Advanced		
ACPI Table/Features Control	Enable/Disable ACPI S3 State	
DSDT - ACPI S3	<Disabled>	
F1 Help	↑ ↓ Select	F5/F6 Change Values
Esc Exit	← Select Menu	Enter Select ► SubMenu
		F9 Setup Defaults
		F10 Save and Exit

ACPI Table/Features Control

Select ACPI sleep state the system will enter when the SUSPEND button is pressed.

The optional settings: DSDT - ACPI S3 (Suspend to RAM), Enabled or Disabled(default)

4-7 Security

InsydeH20 Setup Utility		Rev. 5.0
Main	Advanced	Security
Supervisor Password		Not Install
Set Supervisor Password		Install or Change the password and the length of password must be greater than one character.
F1 Help	↑ ↓ Select	F5/F6 Change Values
Esc Exit	← Select Menu	Enter Select ► SubMenu
		F9 Setup Defaults
		F10 Save and Exit

Supervisor Password

To set up an Supervisor password

1. Select Supervisor Password.

The screen then pops up an Create New Password dialog.

2. Enter your desired password that is no less than 3 characters and no more than 10 characters.
3. Hit [Enter] key to submit.

4-8 Power

InsydeH20 Setup Utility			Rev. 5.0		
Main	Advanced	Security	Power	Boot	Exit
Wake on LAN	<Disabled>	Determines the action take when the system power is off and a PCI Power Management Enable wake up event occurs.			
Power Button	<Instant OFF>				
F1 Help	↑ ↓ Select	F5/F6 Change Values	F9 Setup Defaults		
Esc Exit	← Select Menu	Enter Select ► SubMenu	F10 Save and Exit		

Wake on LAN

Determines the action taken when the system power is off and the PCI power management Enable wake up event occurs.

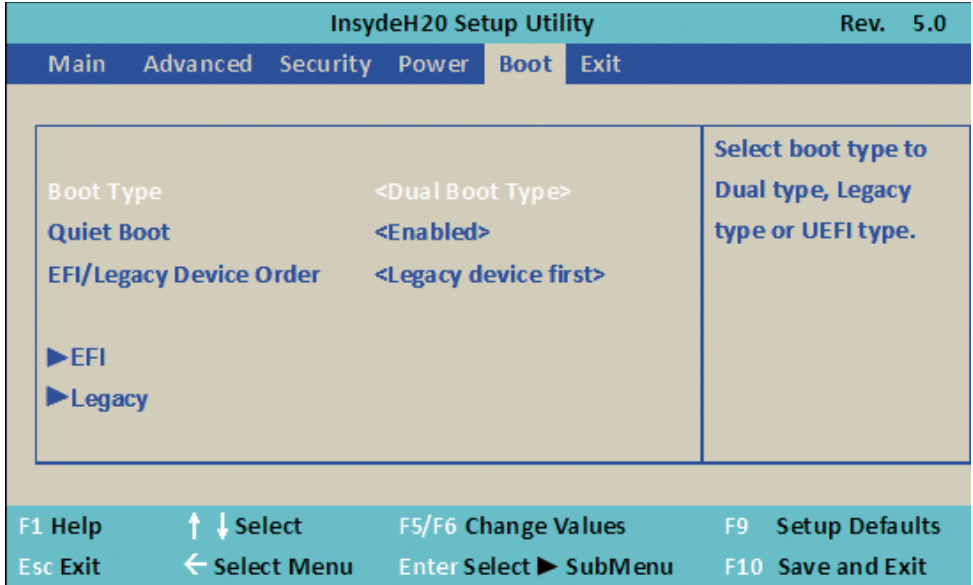
The optional settings: Enabled, Disabled(default)

Power Button

Instant OFF(default) : The system will be turn off directly when push the power button.

Delay 4 sec : The system will be turn off when push the power button for 4 sec.

4-9 Boot



Boot type

Select boot type for Dual type ,Legacy boot type or UEFI boot type, default is Dual boot type

Quiet Boot

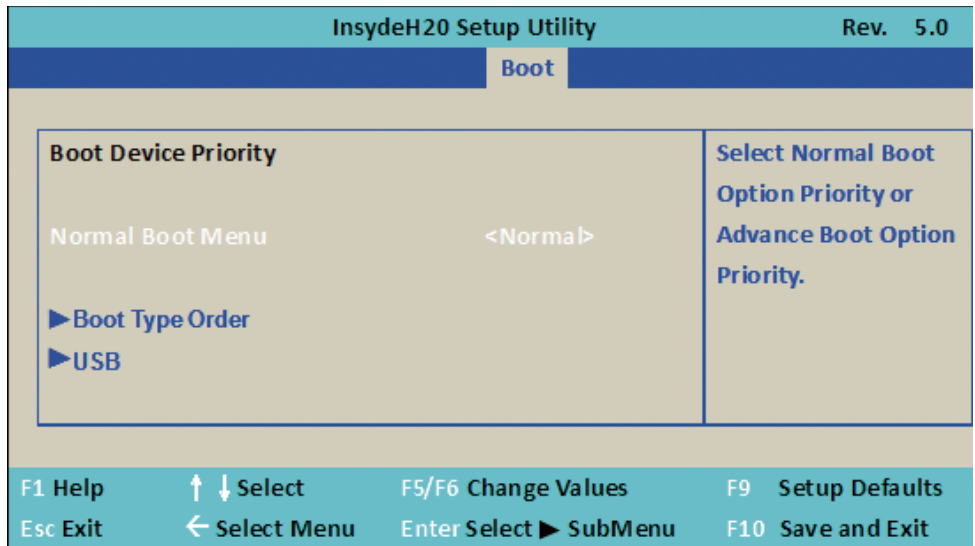
The optional settings are: Enabled(default), Disabled.

EFI / Legacy Device order

Determine EFI device first or legacy device first.

The optional settings: EFI device first, Legacy device first(default), smart mode

4-9-1 Legacy

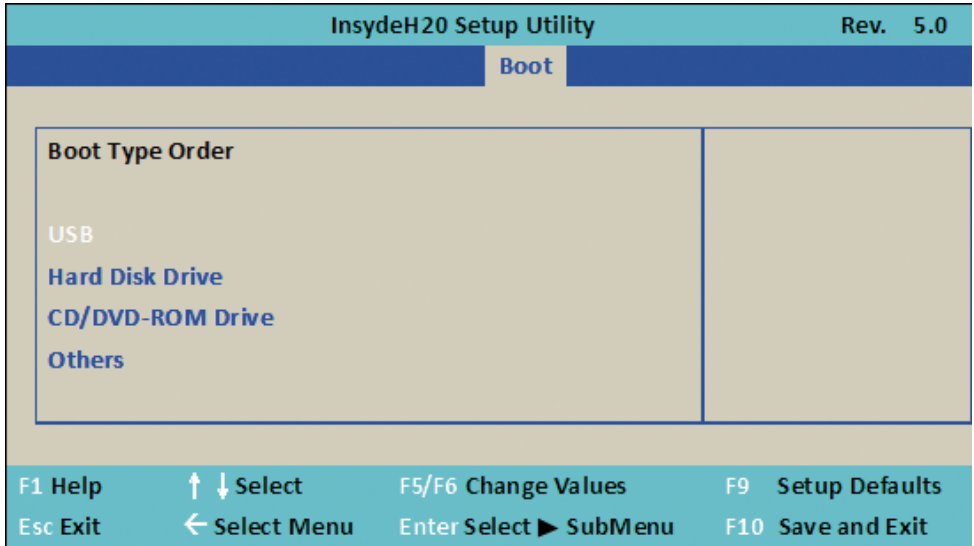


Normal Boot Menu

Select Normal Boot option priority or Advance Boot option priority.

The optional settings: Normal(default), Advance

4-9-2 Boot Type Order

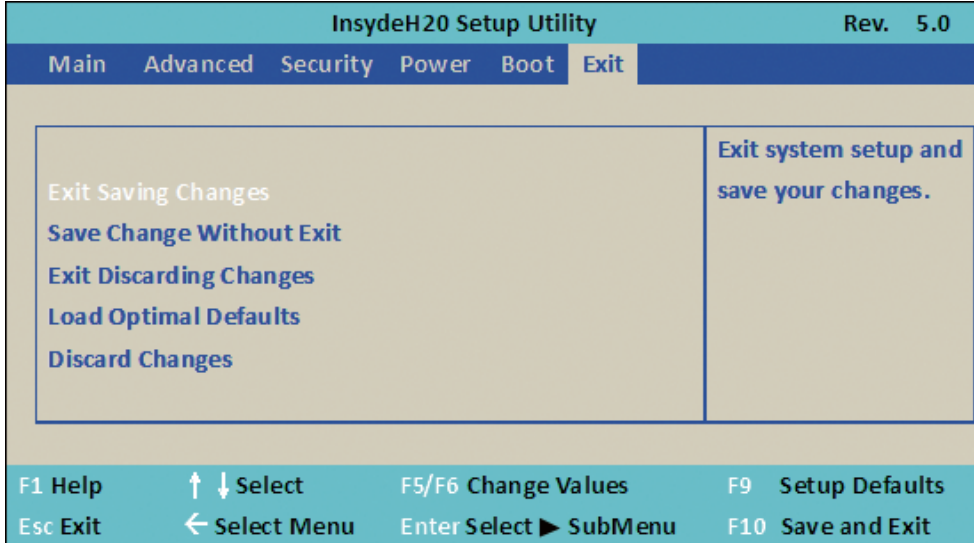


Boot Type Order

Setting the boot type priority.

The default settings is 1.USB drive 2.Hard Disk Drive 3.CD/DVD ROM drive 4.Others

4-10 EXIT



Exit Saving Changes

This item allows user to reset the system after saving the changes.

Save Change Without Exit

This item allows user to saving the changes but doesn't restart.

Exit Discard Changes

This item allows user restart the system but no saving the changes

Load Optimal Default

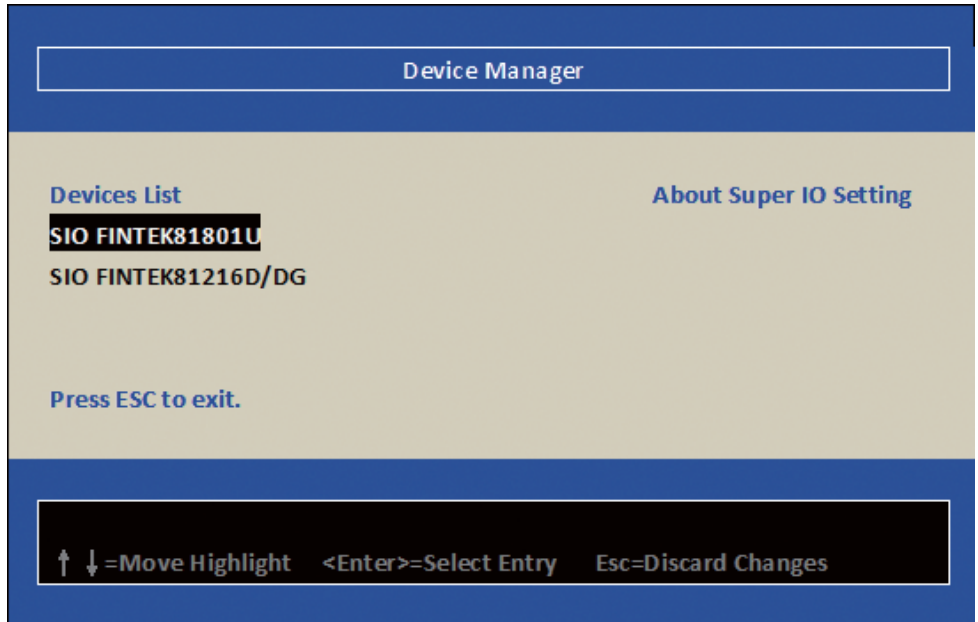
Use this item to restore the optimal default for all the setup options.

Discard Changes

Use this item to cancel all the setup options.

4-11 Device Manager

Please press the key F10 when boot up to go into the Device Manager menu



Serial Port 1/2 Configuration

Please refer section 4-11-1

Serial Port 3/4/5/6 Configuration

Please refer section 4-11-2

4-11-1 SIO FINTEK81801U

SIO FINTEK81801U

Serial Port 1	<Enable>	Configure Serial port
Base I/O Address	<3F8>	using options : Disable
Interrupt	<IRQ4>	No configuration
Serial Mode	<RS232 driver>	[Enable] User
Serial Port 2	<Enable>	configuration [Auto]
Base I/O Address	<2F8>	EFI/OS chooses
Interrupt	<IRQ3>	configuration
Serial Mode	<RS232 driver>	
Power Fail	<Keep State>	
Hardware Monitor		

F9=Reset to Defaults

↑ ↓ =Move Highlight <Enter>=Select Entry Esc=Discard Changes

Serial Port 1/2

Use this item to enable or disable serial port (COM1 or COM2).

The optional settings are: Enabled(default), Disabled.

Serial Port 1 Base IO Address / Interrupt / Serial Mode

Use this item to select an optimal setting for super IO device.

The optional settings are:

IO=3F8h; IRQ=4 (default)

IO=3E8h; IRQ=3,4

IO=2E8h; IRQ=3,4

IO=2F8h; IRQ=3,4

Serial Port 2 Base IO Address / Interrupt / Serial Mode

Use this item to select an optimal setting for super IO device.

The optional settings are:

IO=2F8h; IRQ=3(default)

IO=2E8h; IRQ=3,4

IO=3E8h; IRQ=3,4

IO=3F8h; IRQ=3,4

Serial Mode

RS232 driver(default) : When hardware select to RS232 or RS422 mode,
please enter to RS232 driver.

RS485 driver : When hardware select to RS485 mode,
please enter to RS485 driver. It is the auto flow function for RS485.

Power Failure

This item specifies whether your system will reboot after a power failure or interrupt occurs.

[Keep state] Restores the system to the status before power failure or interrupt occurred. (default)

[Always on] Leaves the computer in the power on state.

[Always off] Leaves the computer in the power off state.

4-11-2 Hardware Monitor

Hardware Monitor

Hardware Monitor

Voltage

VCC3	3.344 V
VCORE	0.560 V
VGFX	0.920 V

Temperature

CPU (°C/°F)	77°C/170 °F
System (°C/°F)	55°C/131 °F

Press [Enter] to view PC health status.

This section shows the status of your CPU, Fan, and overall system.

This is only available when there is Hardware Monitor function onboard.

4-11-3 SIO FINTEK81216D/DG

SIO FINTEK81801U

Serial Port 3	<Enable>	
Base I/O Address	<3E8>	Configure Serial port using options : Disable
Interrupt	<IRQ10>	No configuration
Serial Mode	<RS232 driver>	[Enable] User configuration [Auto]
Sharing Mode	<PCI>	EFI/OS chooses configuration
Serial Port 4	<Enable>	
Base I/O Address	<2E8>	
Interrupt	<IRQ10>	
Serial Mode	<RS232 driver>	
Sharing Mode	<PCI>	

F9=Reset to Defaults
↑ ↓ =Move Highlight <Enter>=Select Entry Esc=Discard Changes

Serial Port 3/4

Use this item to enable or disable serial port (COM3, COM4, COM6 for Touch).
The optional settings are: Enabled(default), Disabled.

Serial Port 3 Base IO Address / Interrupt

Use this item to select an optimal setting for super IO device.
The optional settings are:

IO=3E8h; IRQ=10 (default)

IO=2F8h; IRQ=3,4,5,6,7,10,11

IO=2E8h; IRQ=3,4,5,6,7,10,11

IO=3F8h; IRQ=3,4,5,6,7,10,11

IO=4F8h; IRQ=3,4,5,6,7,10,11

IO=4E8h; IRQ=3,4,5,6,7,10,11

Serial Port 4 Base IO Address / Interrupt

Use this item to select an optimal setting for super IO device.

The optional settings are:

IO=2E8h; IRQ=10(default)

IO=2F8h; IRQ=3,4,5,6,7,10,11

IO=3F8h; IRQ=3,4,5,6,7,10,11

IO=3E8h; IRQ=3,4,5,6,7,10,11

IO=4F8h; IRQ=3,4,5,6,7,10,11

IO=4E8h; IRQ=3,4,5,6,7,10,11

Serial Mode

RS232 driver: When hardware select to RS232 or RS422 mode, (COM1 to COM3 default RS232) please enter to RS232 driver.

RS485 driver : When hardware select to RS485 mode, please enter to RS485 driver. It is the auto flow function for RS485. (COM4 default RS485)

Sharing Mode

This item is OS serial port with sharing mode issue.

If use Linux OS this item should be ISA mode

If use Windows OS this item should be PCI mode

Note: Windows don't set to ISA mode.

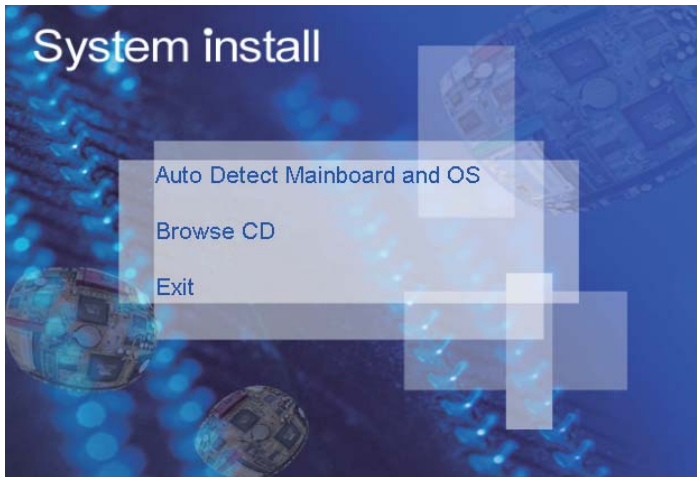
Chapter-5

DRIVER INSTALLATION

There is a system installation DVD in the package. This DVD does not only include all the drivers you need but also some other free application programs and utility programs. In addition, this DVD also includes an auto detect software telling you which hardware is installed and which driver is needed so that your system can function properly. We call this auto detect software SYSTEM INSTALL.

SYSTEM INSTALL Supports Windows 7(32bit/64bit) / Windows 8/8.1(32bit/64bit)

Insert the DVD into your DVD-ROM drive and the SYSTEM INSTALL menu should appear as below. If the menu does not appear, double-click MY COMPUTER and double-click DVD-ROM drive or click START, click RUN, and type X:\SETUP.EXE (assuming your DVD-ROM drive is X).



Make your selection from SYSTEM INSTALL menu:

1. Auto Detect Main board and OS to AUTOMATIC DRIVER INSTALLATION menu
2. Browse DVD to view the contents of the DVD
3. Exit to exit SYSTEM INSTALL menu

Bay Trail for Windows 8.1 (x64)

1. INF

4. LAN

2. VGA

5. TXE

3. HD Audio

6. MBI

[Back to previous page](#)

Bay Trail for Windows 7 (x64)

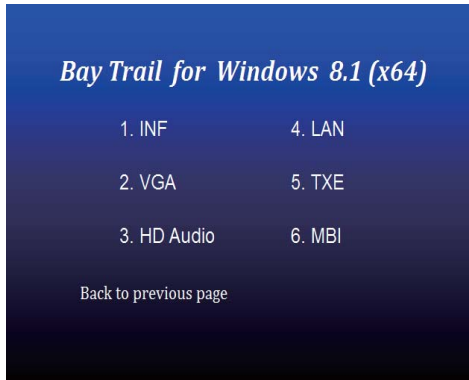
- | | |
|--------------|--------------|
| 1. INF | 5. HD Audio |
| 2. VGA | 6. LAN |
| 3. Serial IO | 7. TXE Patch |
| 4. xHCI | 8. TXE |

[Back to previous page](#)

1. INF Install Intel Baytrail chipset driver
2. VGA Install onboard VGA driver
3. Serial IO Install Serial IO driver (FOR Win 7 only)
4. xHCI Install Intel USB 3.0 xHCI driver (FOR Win 7 only)
5. HD Audio Install HD Audio Codec driver
6. MBI Install MBI driver (FOR Win 8/8.1 only)
7. LAN To the LAN driver Readme file
8. TXE Patch Install Intel TXE patch (FOR Win 7 only)
9. TXE Install Intel TXE driver

Each selection is illustrated below:

5-1 INF Install Intel Baytrail Chipset Driver (example for WIN8 64bit)



1. At the "AUTOMATIC DRIVER INSTALLATION menu" screen, click "INF".



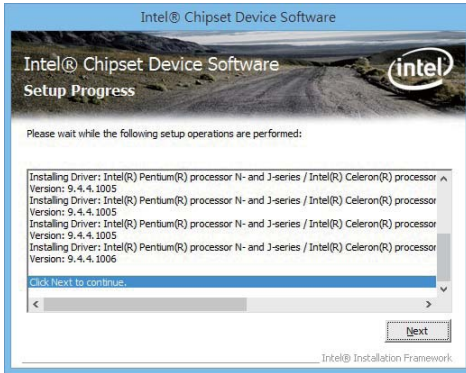
2. At the "Intel® Chipset Device Software" screen, click "Next".



3. At the "License Agreement" screen, click "Yes".



4. At the "Readme File Information" screen, Click "Next".



5. Click "Next"



6. Click "Finish" & restart computer.

NOTE: SYSTEM INSTALL will auto detect file path

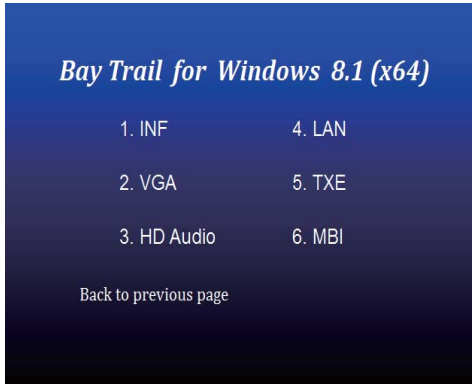
For Windows 7 64/32-bit,

X:\driver\INTEL\BAY\INF\WIN7\infinst_autol.exe

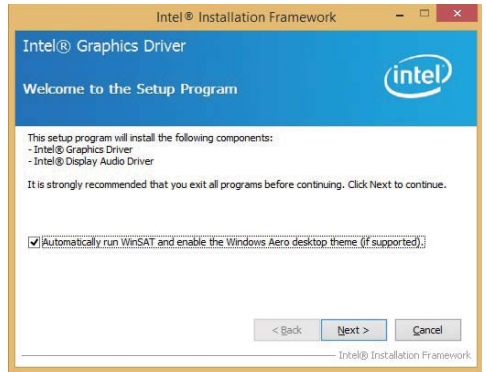
For Windows 8 / 8.1 32/64-bit

X:\driver\INTEL\BAY\INF\WIN_8_64\infinst_autol.exe

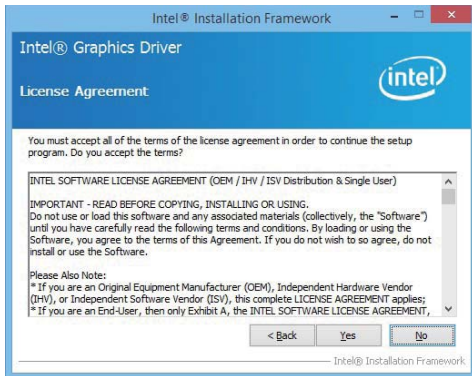
5-2 VGA Install Intel Baytrail VGA Driver (example for WIN8 64bit)



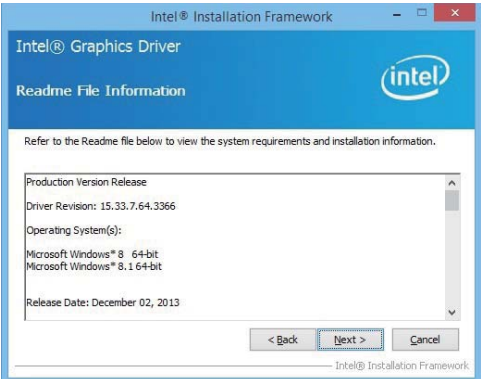
1. At the "AUTOMATIC DRIVER INSTALLATION menu" screen, click "VGA".



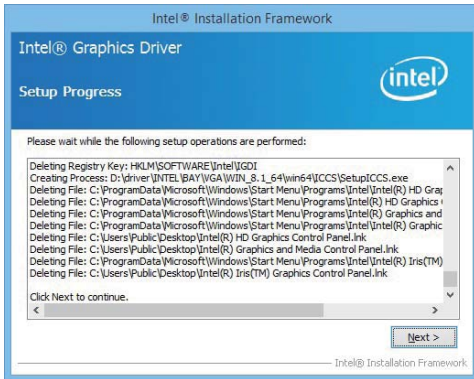
2. At the "Welcome to the Setup Program screen, Click "Next".



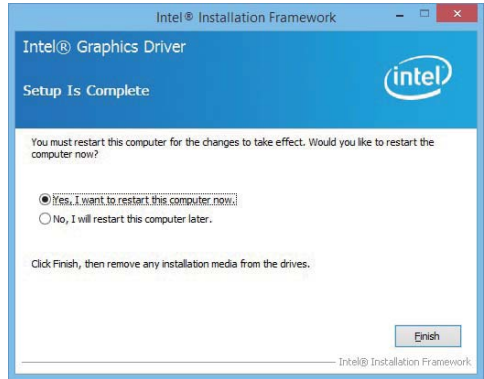
3. At the "License Agreement" screen, Click "Yes"



4. At the "Readme File Information" screen, Click "Next"



5. At the "Setup Progress" screen,
Click "Next".



6. Click "Finish" to restart computer

NOTE: SYSTEM INSTALL will auto detect file path

For Windows 7 32-bit,

X:\driver\INTEL\BAY\VGA\WIN_7_32\Setup.exe

For Windows 7 64-bit

X:\driver\INTEL\BAY\VGA\WIN_7_64\Setup.exe

For Windows 8 / Windows 8.1 32-bit

X:\driver\INTEL\BAY\VGA\WIN_8_32\Setup.exe

For Windows 8 / Windows 8.1 64-bit

X:\driver\INTEL\BAY\VGA\WIN_8_64\Setup.exe

5-3 Serial IO Install Driver Baytrail Serial IO Driver (FOR Windows 7 only)



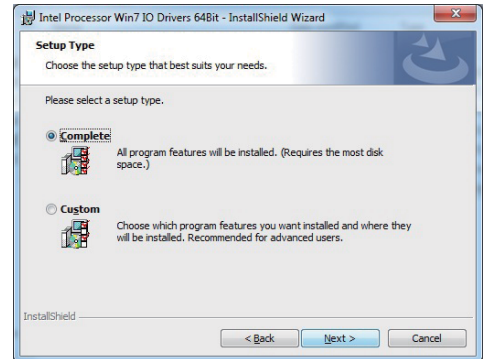
1. At the "AUTOMATIC DRIVER INSTALLATION menu" screen, click "Serial IO".



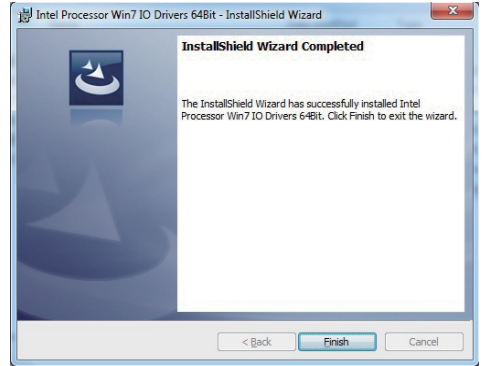
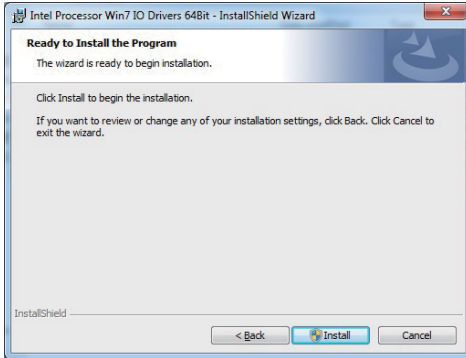
2. At the "Welcome to the Setup Programs" screen, Click "Next".



3. At the "License Agreement" screen, Click "Yes"



4. At the "Setup type" screen, select "complete" and Click "Next".



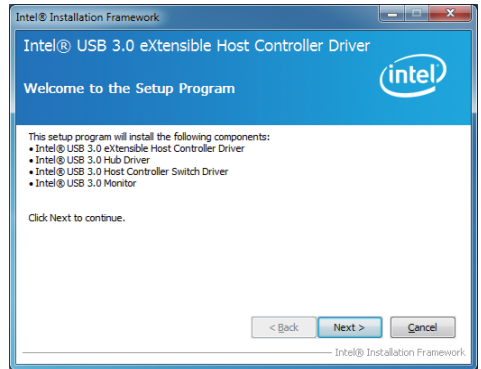
5. At the "Ready to install the program" screen, Click "Install"
6. Click "Finish" and restart computer

NOTE: SYSTEM INSTALL will auto detect file path
For Windows 7 32-bit,
X:\driver\INTEL\BAY\SERIALIO\WIN7_32Bit.msi
For Windows 7 64-bit
X:\driver\INTEL\BAY\SERIALIO\Win7_64Bit.msi

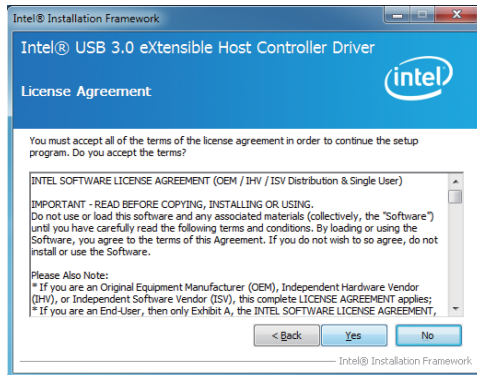
5-4 xHCI Install Intel USB 3.0 xHCI Driver (FOR Windows 7 only)



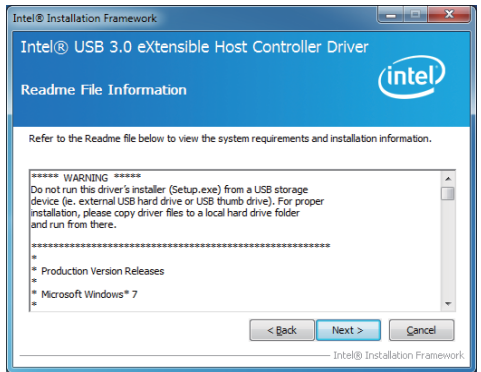
1. At the "AUTOMATIC DRIVER INSTALLATION menu" screen, Click "USB 3.0"



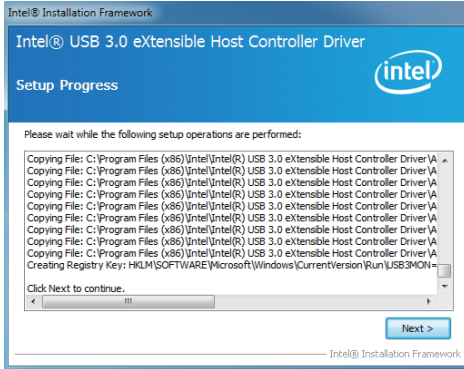
2. At the "Intel® USB 3.0 extensible Host Controller Driver" screen, Click "Next".



3. At the "License Agreement" screen, Click "Yes".



4. At the "Readme File Information" screen, Click "Next".



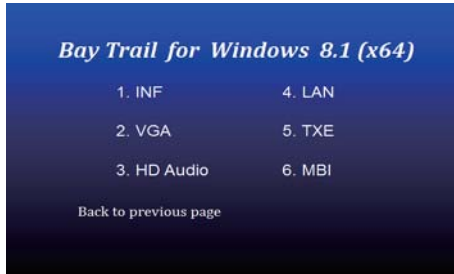
5. At the "Setup Progress" screen, Click "Next". 6. Click "Finish" to restart computer

NOTE: SYSTEM INSTALL will auto detect file path

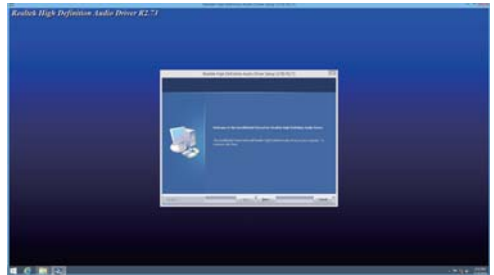
For Windows 7 32 / 64-bit,

X:\driver\INTEL\BAY\XHC\Driver_Installer\Setup.exe

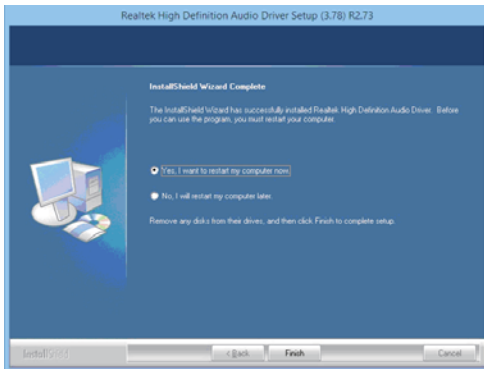
5-5 HD Audio Install High Definition Audio Driver (example for WIN8 64bit)



1. At the "AUTOMATIC DRIVER INSTALLATION" menu, click "HD Audio"



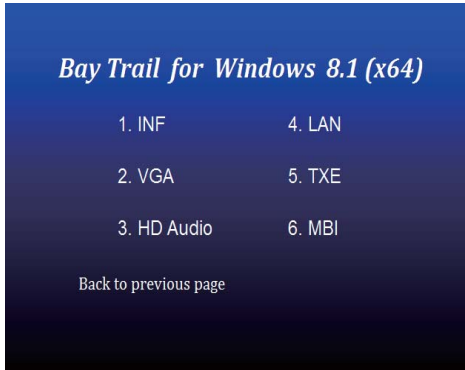
2. Click "Next".



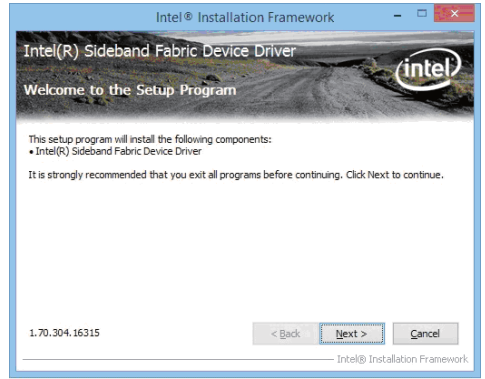
3. Click "Finish" to restart computer

NOTE: SYSTEM INSTALL will auto detect file path
For Windows 7 32 / 64-bit, Windows 8/8.1 32 / 64-bit
X:\driver\INTEL\BAY\SOUND\Win7_Win8_Win81_R273.exe

5-6 MBI Install Intel MBI Driver (FOR Win 8/8.1 only)



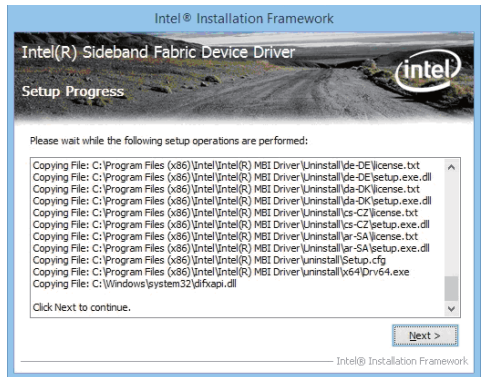
1. At the "AUTOMATIC DRIVER INSTALLATION menu", click "HD Audio"



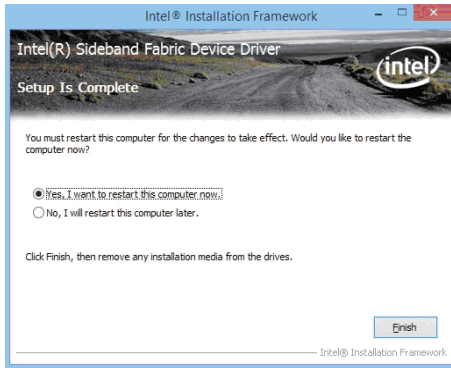
2. At the "Welcome to the Setup Program screen, Click "Next".



3. At the "License Agreement" screen, Click "Yes".



4. At the "Setup Progress" screen, Click "Next".



5. Click "Finish" to restart computer

NOTE: SYSTEM INSTALL will auto detect file path

For Windows 8/8.1 32 / 64-bit,

X:\driver\INTEL\BAY\MBI\Setup.exe

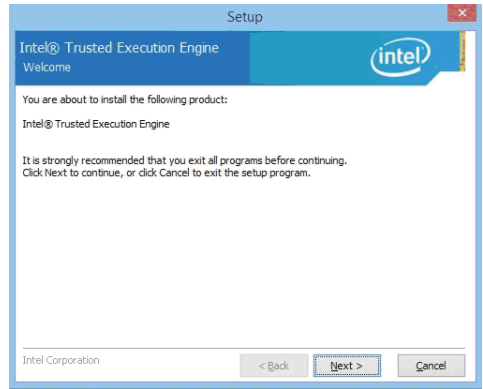
5-7 TXE Install Intel TXE driver

5-7-1 TXE Install for WIN8/WIN8.1

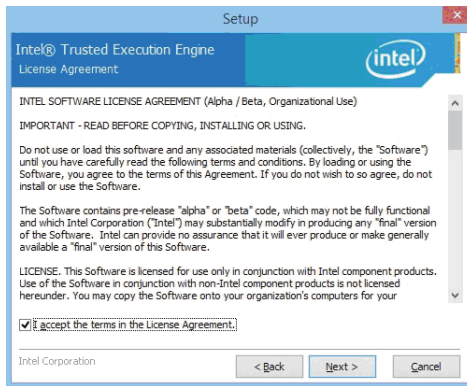
Bay Trail for Windows 8.1 (x64)

1. INF	4. LAN
2. VGA	5. TXE
3. HD Audio	6. MBI

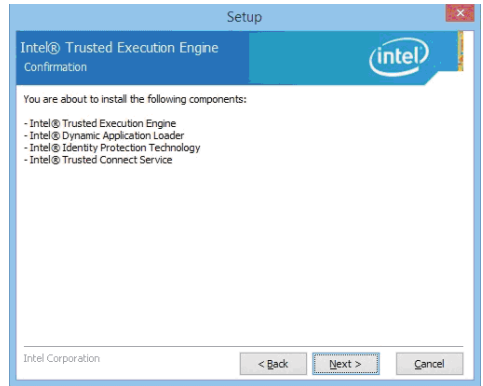
Back to previous page



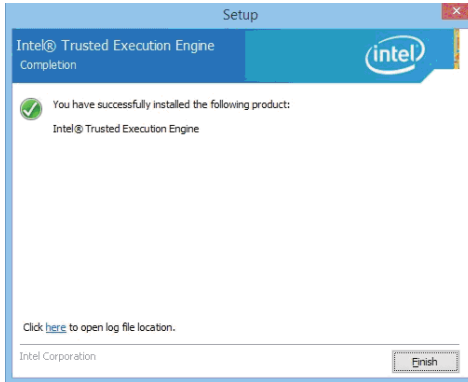
1. At the "AUTOMATIC DRIVER INSTALLATION menu", click "TXE"
2. At the "Setup" screen, Click "Next".



3. At the "License Agreement" screen, Click "Yes".



4. Click "Next".



5. Click “Finish” & restart computer

NOTE: SYSTEM INSTALL will auto detect file path

For Windows 8 32 / 64-bit,

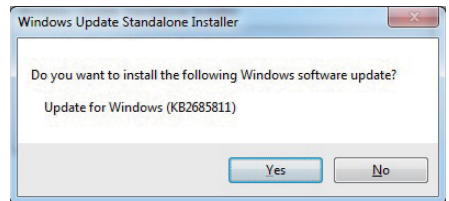
X:\driver\INTEL\BAY\TXE\WIN_8\SetupTXE.exe

For Windows 8.1 32 / 64-bit,

X:\driver\INTEL\BAY\TXE\WIN_8.1\SetupTXE.exe

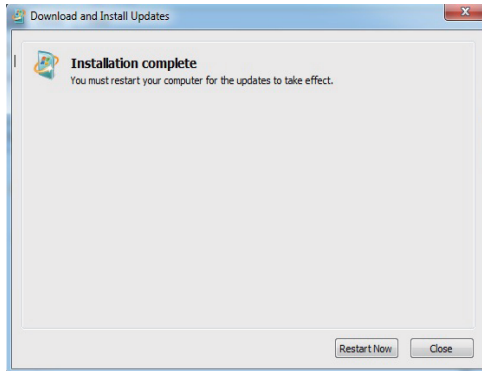
5-7-2 TXE Install for WIN7

Please install PXE Patch first.



1. At the "AUTOMATIC DRIVER INSTALLATION menu", click "TXE Patch "

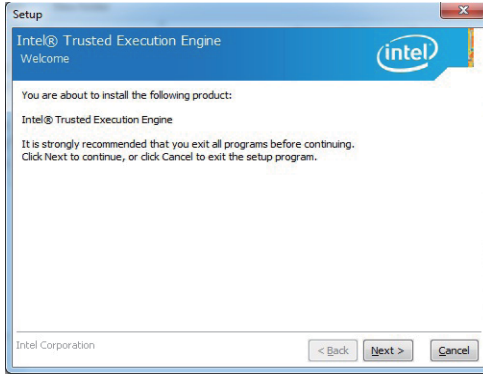
2. At the "Windows Update" screen, Click "Yes".



3. Click "Finish" & restart computer



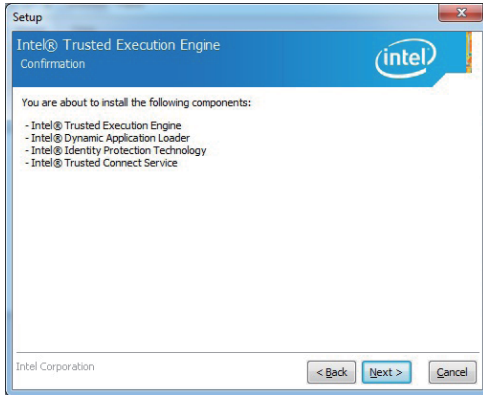
4. At the "AUTOMATIC DRIVER INSTALLATION menu", click "TXE "



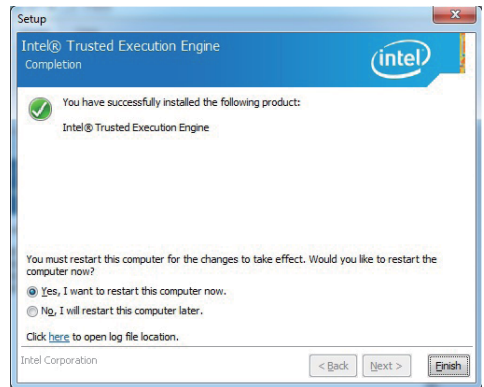
5. At the "TXE Setup" screen, Click "Next".



6. At the "License Agreement" screen, Click "Yes".



7. Click "Next".



8. Click "Finish" & restart computer

NOTE: SYSTEM INSTALL will auto detect file path

For Windows 7 32 / 64-bit,

TXE Patch

X:\driver\INTEL\BAY\TXE\WIN_7\kmdf-1.11-Win-6.1-x86.msu

X:\driver\INTEL\BAY\TXE\WIN_7\kmdf-1.11-Win-6.1-x64.msu

TXE

X:\driver\INTEL\BAY\TXE\WIN_7\SetupTXE.exe

X:\driver\INTEL\BAY\TXE\WIN_7\SetupTXE.exe

5-8 How to update Insyde BIOS

Under DOS Mode

STEP 1. Prepare a bootable disc.

(Storage device could be USB FDD or USB pen drive.)

STEP 2. Copy utility program to your bootable disc. You may download it from our website.

STEP 3. Copy the latest BIOS for your LEX motherboard from our website to your bootable disc.

STEP 4. (Here take 2I385AC as an example, please enter your motherboard's name)

Insert your bootable disc into X: (X could be C:, A: or others.

It depends on which type of storage device you use.)

Start the computer and type

X:\: H2OFFT-D.EXE 2I385ACA2.ROM -BIOS -ALL

2I385ACA2.ROM is the file name of the latest BIOS.

It may be 2I385ACA1.ROM or 2I385ACA2.ROM, etc.

Please leave one space between .ROM & -BIOS -ALL

By Bay Trail series mainboard, please type

X:\: H2OFFT-D.EXE 2I385ACA2.ROM -BIOS -ALL

-BIOS : Flash BIOS region

-ALL : Flash all

STEP 5. Press ENTER and the BIOS will be updated,

Computer will restart automatically.

Appendix A: Power Consumption Test

Condition (2I385A/CW--E3815)

Item	Spec
CPU	Atom E3815 1.46 Ghz
Memory	DDR3L 1066 2GB
Operating System	Windows 7 / SP1
Test Program	3D Mark 06
HDD 2.5" SATA	Slim Type HDD
mSATA	24GB/32GB

Test Result for reference only !

Model Name	Storage	Power off	Start up		Operation Maximum	Shut down Maximum	In Put Voltage
			Maximum	Stable			
2I385A	Slim Type HDD	0.10A	0.75A	0.51A	0.89A	0.69A	12V
	mSATA	0.10A	0.59A	0.49A	0.76A	0.58A	12V
2I385CW	Slim Type HDD	0.14A	0.91A	0.67A	0.99A	0.78A	12V
		0.09A	0.47A	0.33A	0.52A	0.40A	24V
	mSATA	0.14A	0.78A	0.61A	0.84A	0.66A	12V
		0.09A	0.42A	0.31A	0.46A	0.35A	24V

The power consumption depends on your device choice!

Condition (2I385A/CW--E3845)

Item	Spec
CPU	Atom E3845 1.91 Ghz
Memory	DDRL 1333 4GB
Operating System	Windows 7 / SP1
Test Program	3D Mark 06
HDD 2.5" SATA	Slim Type HDD
mSATA	24GB/32GB

Test Result for reference only !

Model Name	Storage	Power off	Start up		Operation Maximum	Shut down Maximum	In Put Voltage
			Maximum	Stable			
2I385A	Slim Type HDD	0.10A	0.96A	0.66A	1.13A	0.80A	12V
	mSATA	0.09A	0.81A	0.55A	1.06A	0.72A	12V
2I385CW	Slim Type HDD	0.14A	1.06A	0.68A	1.22A	0.90A	12V
		0.09A	0.57A	0.35A	0.63A	0.47A	24V
	mSATA	0.14A	0.95A	0.62A	1.10A	0.82A	12V
		0.09A	0.50A	0.32A	0.57A	0.42A	24V

The power consumption depends on your device choice!

Appendix B: Resolution list

640 x 480 x (256 / 16bit / 32bit)
800 x 600 x (256 / 16bit / 32bit)
1024 x 768 x (256 / 16bit / 32bit)
1152 x 864 x (256 / 16bit / 32bit)
1280 x 600 x (256 / 16bit / 32bit)
1280 x 720 x (256 / 16bit / 32bit)
1280 x 768 x (256 / 16bit / 32bit)
1280 x 800 x (256 / 16bit / 32bit)
1280 x 960 x (256 / 16bit / 32bit)
1280 x 1024 x (256 / 16bit / 32bit)
1400 x 1050 x (256 / 16bit / 32bit)
1440 x 900 x (256 / 16bit / 32bit)
1600 x 900 x (256 / 16bit / 32bit)
1600 x 1200 x (256 / 16bit / 32bit)
1680 x 1050 x (256 / 16bit / 32bit)
1920 x 1080 x (256 / 16bit / 32bit)
1920 x 1200 x (256 / 16bit / 32bit)